

is space time? a spatio-temporal theory of transitional turbulence

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*Quantum-Classical Transition in Many-Body Systems: Indistinguishability,
Interference and Interactions*

Max Planck Institute for the Physics of Complex Systems, Dresden

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overview

- ① what this talk is about
- ② “turbulence” in small domains
- ③ “turbulence” in infinite spatial domains
- ④ space is time
- ⑤ bye bye, dynamics

this talk is about¹

how to solve

strongly nonlinear field theories

¹references in this presentation are hyperlinked

do clouds solve PDEs?

do clouds integrate Navier-Stokes equations?

NO!



⇒ other swirls ⇒



do clouds satisfy Navier-Stokes equations?

yes!

they satisfy them **locally**, everywhere and at all times

part 1

- ① “turbulence” in small domains
- ② “turbulence” in infinite spatial domains
- ③ space is time
- ④ bye bye, dynamics

goal : go from equations to turbulence

Navier-Stokes equations

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \frac{1}{R} \nabla^2 \mathbf{v} - \nabla p + \mathbf{f}, \quad \nabla \cdot \mathbf{v} = 0,$$

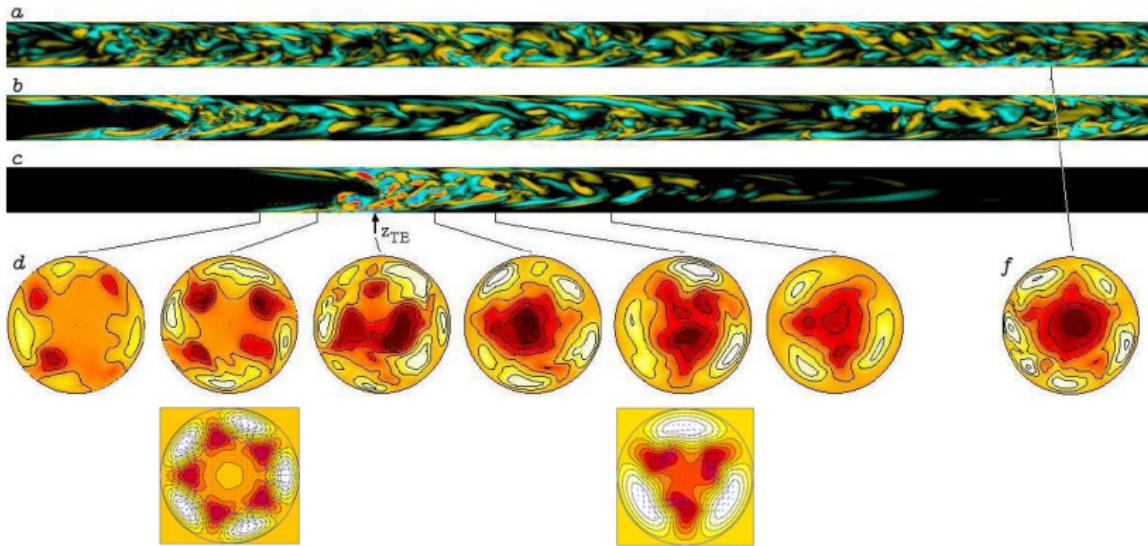
velocity field $\mathbf{v} \in \mathbb{R}^3$; pressure field p ; driving force \mathbf{f}

describe turbulence

starting from the equations (no statistical assumptions)

example : pipe flow²

amazing data! amazing numerics!



²B. Hof et al., Science 305, 1594–1598 (2004).

dynamical description of turbulence

state space

a manifold $\mathcal{M} \in \mathbb{R}^d$: d numbers determine the state of the system

representative point

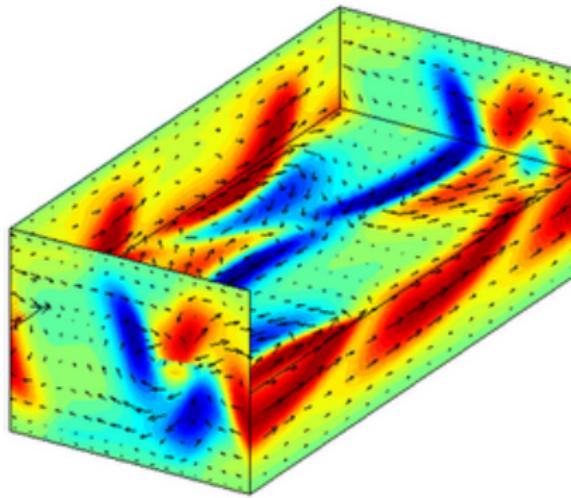
$x(t) \in \mathcal{M}$

a state of physical system at instant in time

integrate forward in time

trajectory $x(t) = f^t(x_0)$ = representative point time t later

plane Couette : so far, **small** computational cells³



velocity field visualization

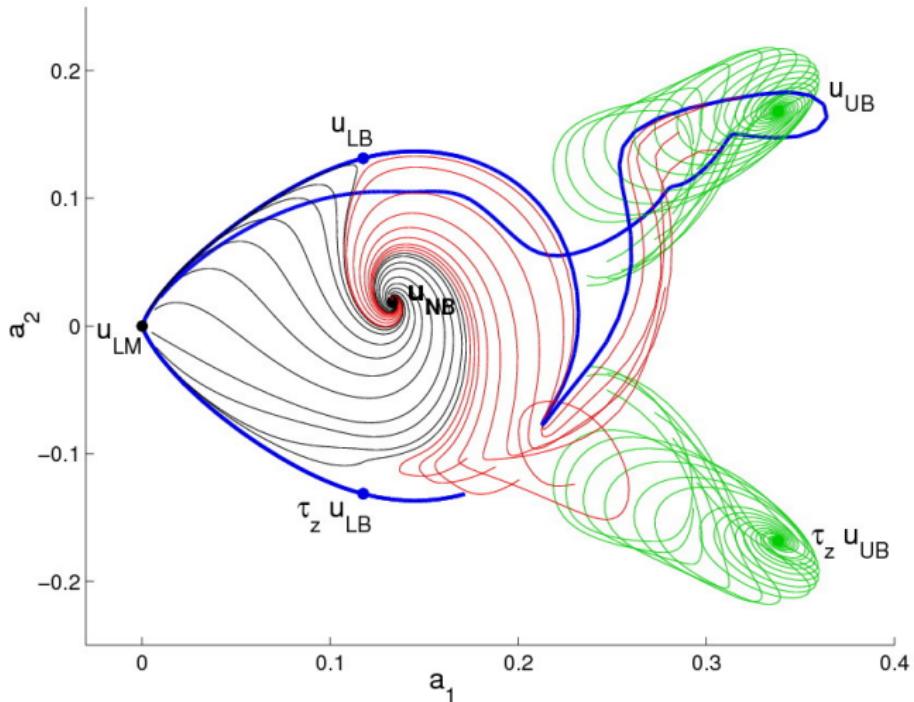
John F Gibson (U New Hampshire)

Jonathan Halcrow (Google)

P. C. (Georgia Tech)

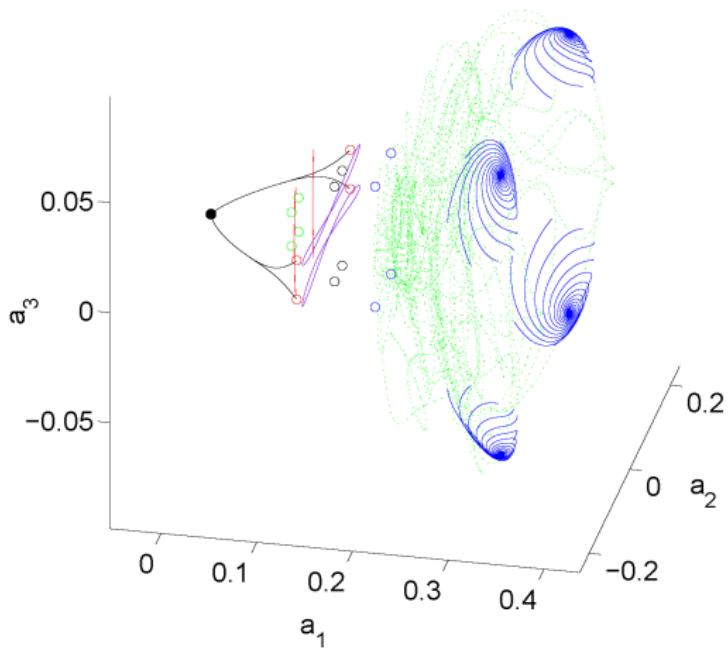
³J. F. Gibson et al., J. Fluid Mech. 611, 107–130 (2008).

can visualize 61,506 dimensional state space of turbulent flow



equilibria of turbulent plane Couette flow,
their unstable manifolds, and
myriad of turbulent videos mapped out as one happy family

plane Couette state space $10^5 \rightarrow 3D$



equilibria, periodic orbits, their (un)stable manifolds
shape the turbulence

problem

unable to compute invariant solutions for large spatial domains⁴

solutions on large domains are too unstable

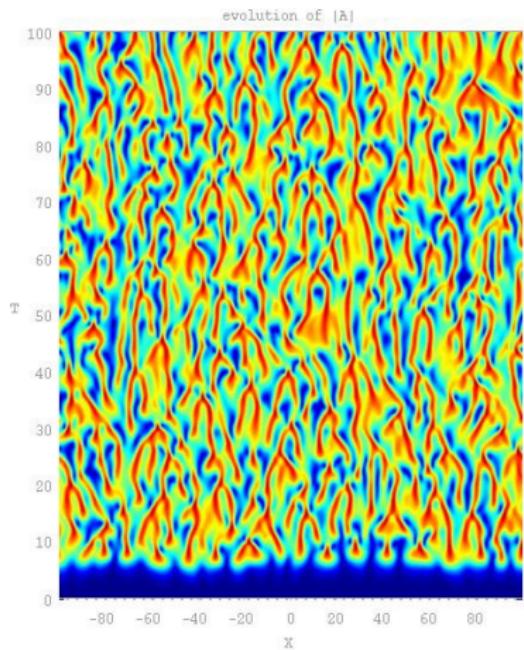
⁴A. P. Willis et al., "Relative periodic orbits form the backbone of turbulent pipe flow", In preparation., 2015.

part 2

- ① “turbulence” in small domains
- ② **“turbulence” in infinite spatial domains**
- ③ space is time
- ④ bye bye, dynamics

next: large space-time domains

example : complex Ginzburg-Landau on a large domain



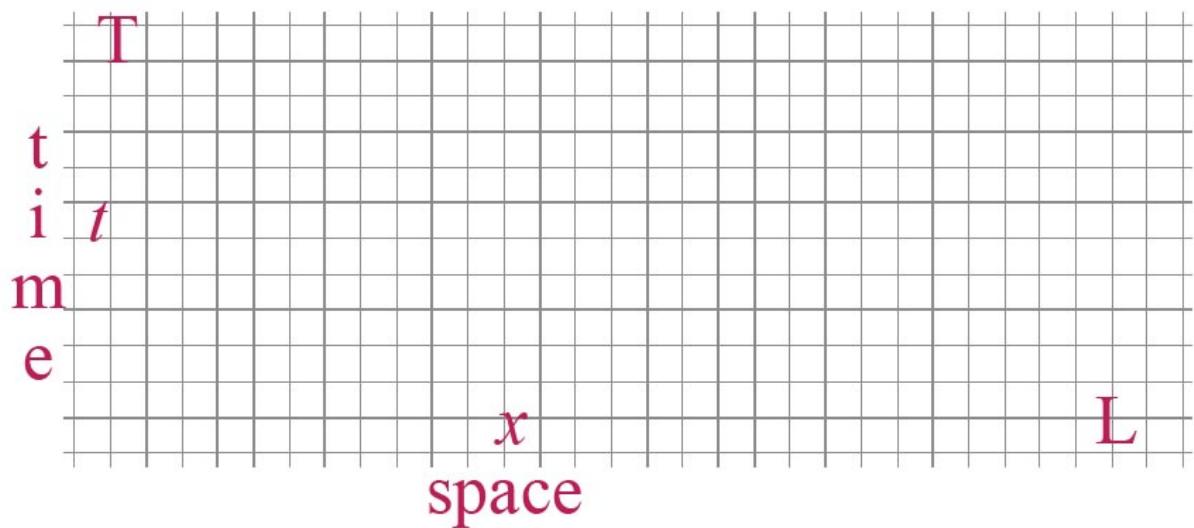
[horizontal] space x

[up] time evolution

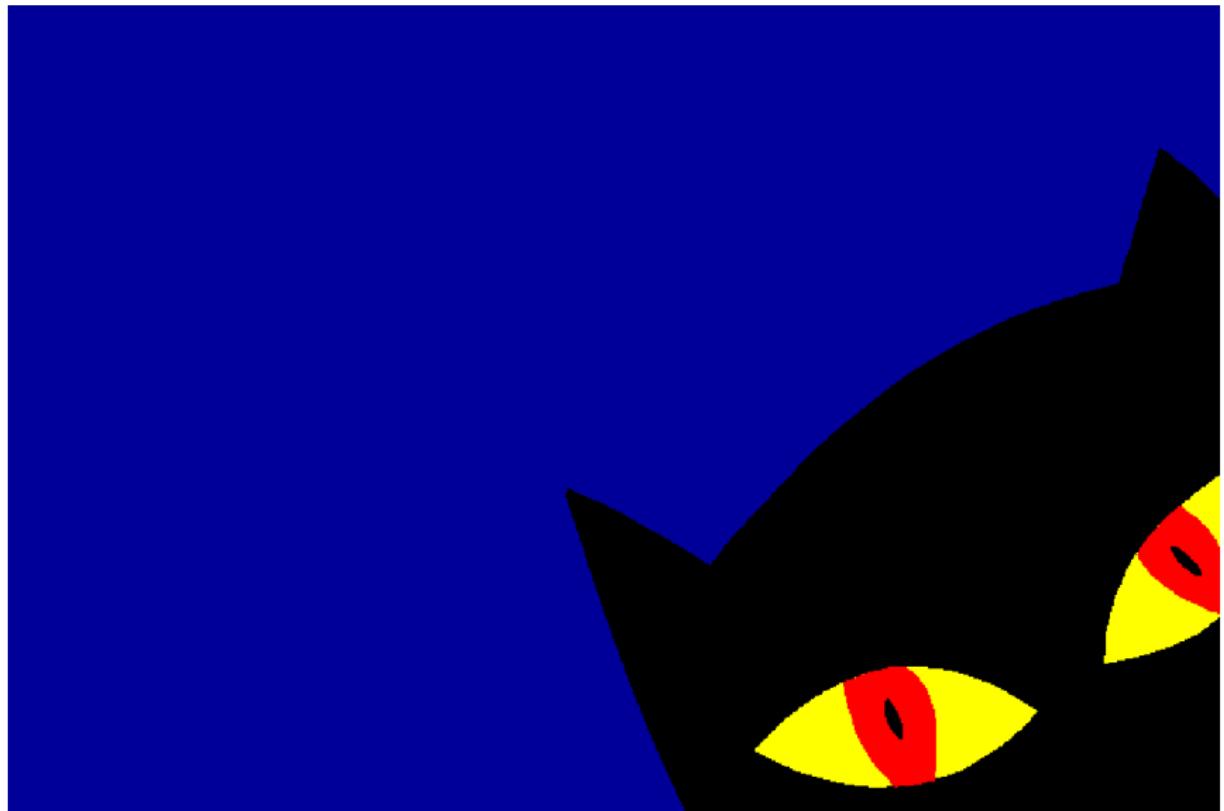
challenge : describe $(x, t) \in (-\infty, \infty) \times (-\infty, \infty)$

continuous symmetries : space, time translations

spacetime discretization

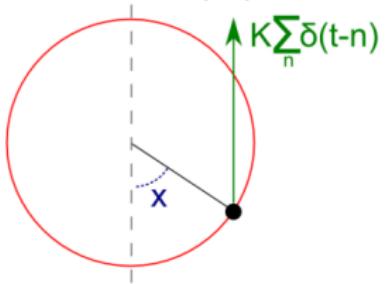


1) chaos and a single kitten



example of a “small domain dynamics” : kicked rotor

an electron circling an atom, subject to
a discrete time sequence of angle-dependent kicks $F(x_t)$



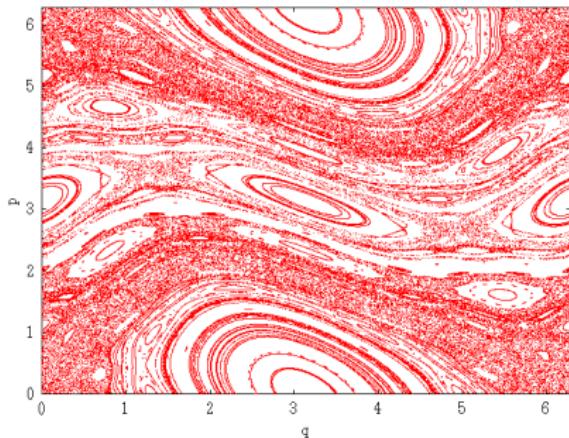
Taylor, Chirikov and Greene standard map

$$\begin{aligned}x_{t+1} &= x_t + p_{t+1} \quad \text{mod } 1, \\p_{t+1} &= p_t + F(x_t)\end{aligned}$$

→ chaos in Hamiltonian systems

standard map

example of chaos in a Hamiltonian system



the simplest example : a single kitten in time

force $F(x) = Kx$ linear in the displacement x , $K \in \mathbb{Z}$

$$x_{t+1} = x_t + p_{t+1} \mod 1$$

$$p_{t+1} = p_t + Kx_t \mod 1$$

Continuous Automorphism of the Torus, or
(after same algebra, replacing $K \rightarrow s$, etc)

Hamiltonian cat map

a linear, area preserving map of a 2-torus onto itself

$$\begin{pmatrix} x_{t+1} \\ p_{t+1} \end{pmatrix} = A \begin{pmatrix} x_t \\ p_t \end{pmatrix} \mod 1, \quad A = \begin{pmatrix} s-1 & 1 \\ s-2 & 1 \end{pmatrix}$$

for integer $s = \text{tr } A > 2$ the map is hyperbolic \rightarrow a fully chaotic Hamiltonian dynamical system

cat map in Lagrangian form⁵

replace momentum by velocity

$$p_{t+1} = (x_{t+1} - x_t)/\Delta t$$

dynamics in (x_t, x_{t-1}) state space is particularly simple

2-step difference equation

$$x_{t+1} - s x_t + x_{t-1} = -m_t$$

unique integer m_t ensures that

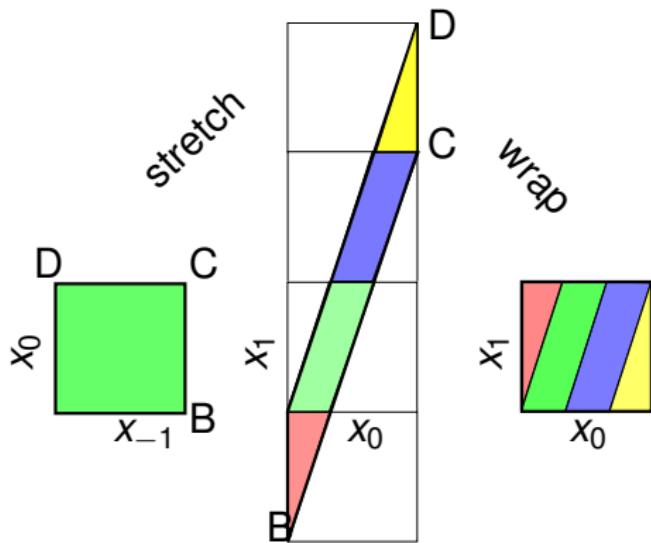
x_t lands in the unit interval at every time step t

nonlinearity : mod 1 operation, encoded in

$$m_t \in \mathcal{A}, \quad \mathcal{A} = \text{finite alphabet of possible values for } m_t$$

⁵I. Percival and F. Vivaldi, Physica D 27, 373–386 (1987).

example : $s = 3$ cat map symbolic dynamics

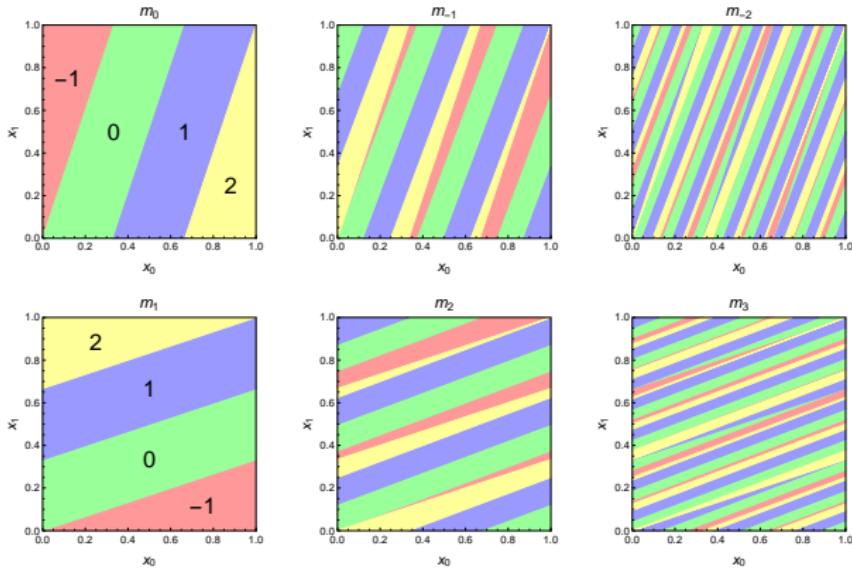


cat map stretches the unit square translations by

$$m_0 \in \mathcal{A} = \{1, 0, 1, 2\} = \{\text{red, green, blue, yellow}\}$$

return stray kittens back to the torus

cat map (x_0, x_1) state space partition



- (a) 4 regions labeled by m_0 . , obtained from (x_{-1}, x_0) state space by one iteration
- (b) 14 regions, 2-steps past $m_{-1}m_0$. (c) 44 regions, 3-steps past $m_{-2}m_{-1}m_0$.
- (d) 4 regions labeled by future . m_1
- (e) 14 regions, 2-steps future . m_1m_2 (f) 44 regions, 3-steps future block $m_3m_2m_1$.

2) chaos and the spatiotemporally infinite cat



N -particle system

spatiotemporal cat map⁶

Consider a 1-dimensional spatial lattice, with field $x_{n,t}$ (the angle of a kicked rotor “particle” at instant t) at site n .

require

- (0) each site couples to its nearest neighbors $x_{n\pm 1,t}$
- (1) invariance under spatial translations
- (2) invariance under spatial reflections
- (3) invariance under the space-time exchange

obtain

2-dimensional coupled cat map lattice

$$x_{n,t+1} + x_{n,t-1} - s x_{n,t} + x_{n+1,t} + x_{n-1,t} = -m_{n,t}$$

⁶B. Gutkin and V. Osipov, Nonlinearity **29**, 325–356 (2016).

herding cats : a Euclidean field theory⁷

convert the spatial-temporal differences to discrete derivatives

discrete d -dimensional Euclidean space-time Laplacian in
 $d = 1$ and $d = 2$ dimensions

$$\square x_t = x_{t+1} - 2x_t + x_{t-1}$$

$$\square x_{n,t} = x_{n,t+1} + x_{n,t-1} - 4x_{n,t} + x_{n+1,t} + x_{n-1,t}$$

→ the cat map equations generalized to

***d*-dimensional spatiotemporal cat map**

$$(\square - s + 2d)x_z = m_z$$

where $x_z \in \mathbb{T}^1$, $m_z \in \mathcal{A}$ and $z \in \mathbb{Z}^d$ = lattice site label

⁷B. Gutkin et al., *A linear symbolic dynamics for coupled cat maps lattices*, In preparation, 2016.

deep insight, derived from observing kittens

an insight that applies to all coupled-map lattices, and all PDEs with translational symmetries

a d -dimensional spatiotemporal pattern

$$\{x_z\} = \{x_z, z \in \mathbb{Z}^d\}$$

is labelled by a *d -dimensional spatiotemporal block of symbols*

$$\{m_z\} = \{m_z, z \in \mathbb{Z}^d\},$$

rather than a *single* temporal symbol sequence

(as is done when describing a small coupled few-“particle” system, or a small computational domain).

“periodic orbits” are now invariant d -tori

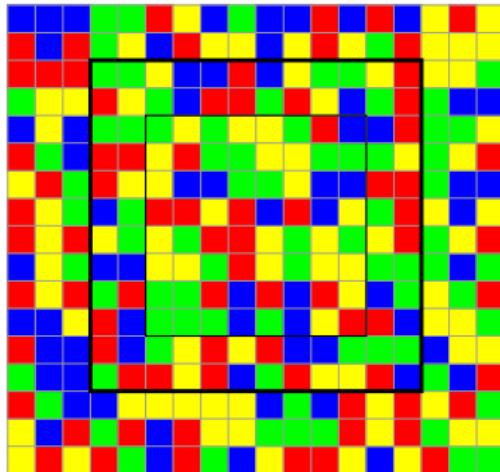
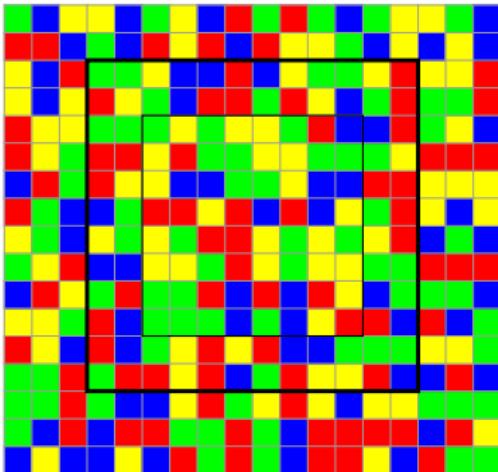
1 time, 0 space dimensions

a state space point is *periodic* if its orbit returns to it after a finite time T ; in time direction such orbit tiles the time axis by infinitely many repeats

1 time, d -1 space dimensions

a state space point is *spatiotemporally periodic* if it belongs to an invariant d -torus \mathcal{R} , i.e., a block $M_{\mathcal{R}}$ that tiles the lattice state M periodically, with period ℓ_j in j th lattice direction

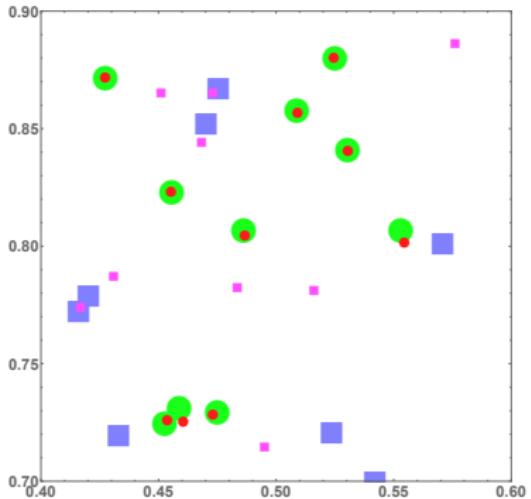
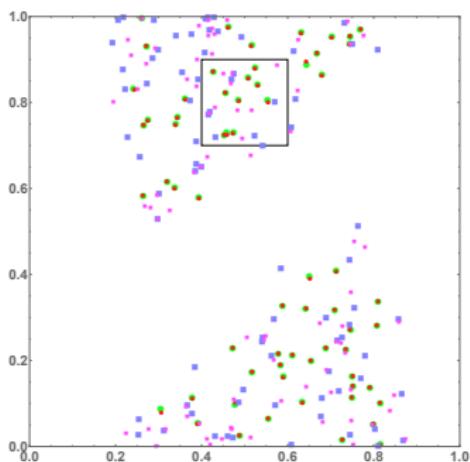
an example of invariant 2-tori : shadowing, symbolic dynamics space



2d symbolic representation of two invariant 2-tori shadowing
each other within the shared block $M_{\mathcal{R}} = M_{\mathcal{R}_0} \cup M_{\mathcal{R}_1}$ (blue)

- border \mathcal{R}_1 (thick black), interior \mathcal{R}_0 (thin black)
- symbols outside \mathcal{R} differ

shadowing, state space



(left) state space points $(x_{0,t}, x_{0,t-1})$ of the two invariant 2-tori
(right) zoom into the small rectangular area
interior points $\in \mathcal{R}_0$ (large green), (small red) circles
border points $\in \mathcal{R}_1$ (large violet), (small magenta) squares
within the interior of the shared block,

the shadowing is exponentially good

conclusion

space, time merely parametrize a given invariant solution

what matters is

the enumeration of distinct invariant solutions

part 3

- ① “turbulence” in small domains
- ② “turbulence” in infinite spatial domains
- ③ **space is time**
- ④ bye bye, dynamics

yes, lattice schmatiz, but

does it work for PDEs?

chronotope⁸

In literary theory and philosophy of language, the chronotope is how configurations of time and space are represented in language and discourse.

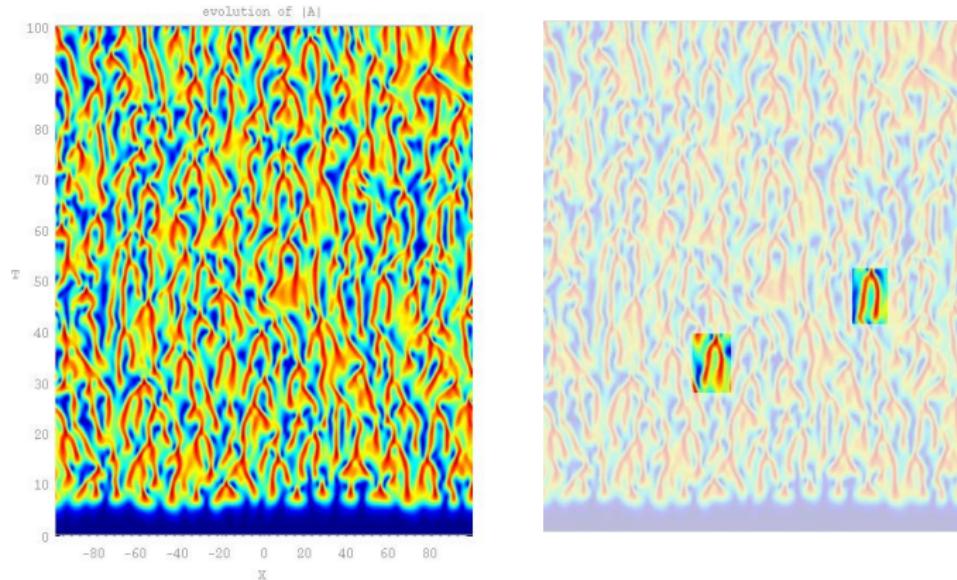
— Wikipedia : Chronotope

- Mikhail Mikhailovich Bakhtin (1937)

⁸S. Lepri et al., J. Stat. Phys. 82, 1429–1452 (1996).

space-time complex Ginzburg-Landau on a large domain

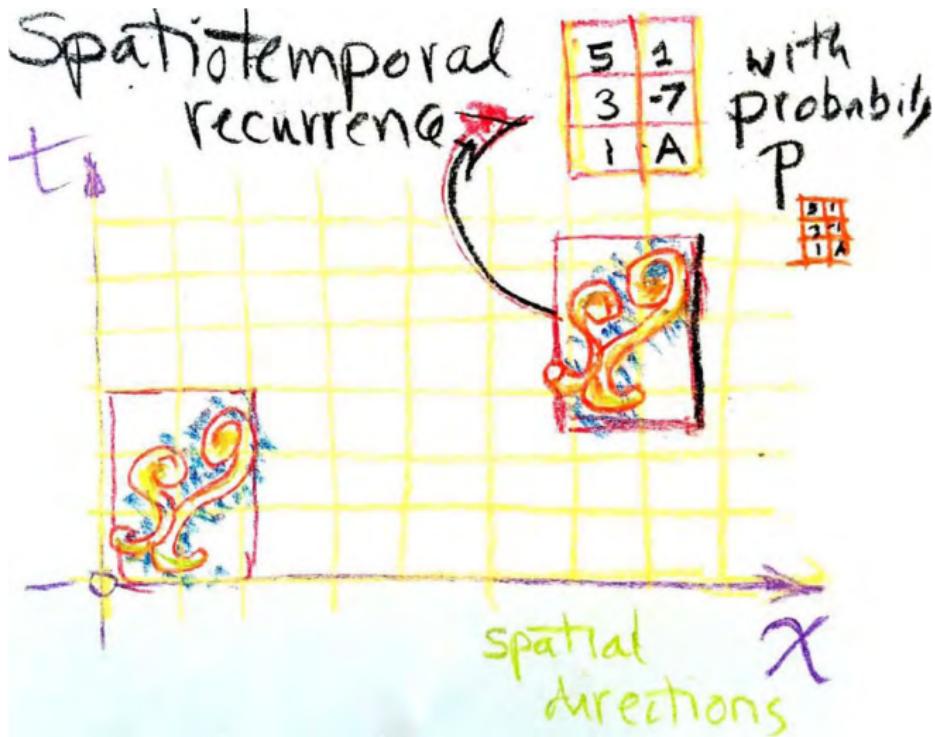
a nearly recurrent chronotope



[horizontal] space $x \in [-L/2, L/2]$

[up] time evolution

must have⁹: 2D symbolic dynamics $\in (-\infty, \infty) \times (-\infty, \infty)$



⁹B. Gutkin and V. Osipov, Nonlinearity **29**, 325–356 (2016).

(1+1) space-time dimensional “Navier-Stokes”

computationally not ready yet to explore the inertial manifold of
(1 + 3)-dimensional turbulence - start instead with
(1 + 1)-dimensional

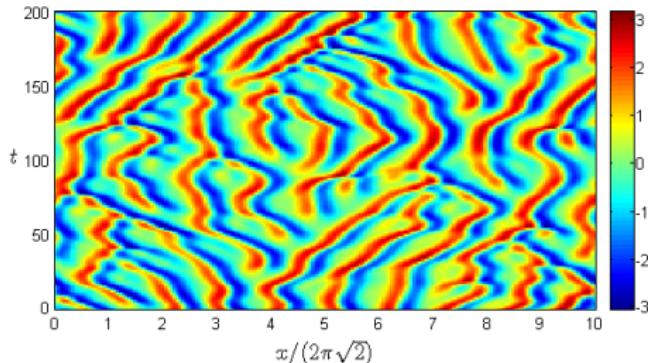
Kuramoto-Sivashinsky time evolution equation

$$u_t + u \nabla u = -\nabla^2 u - \nabla^4 u, \quad x \in [-L/2, L/2],$$

describes spatially extended systems such as

- flame fronts in combustion
- reaction-diffusion systems
- ...

a test bed : Kuramoto-Sivashinsky on a large domain

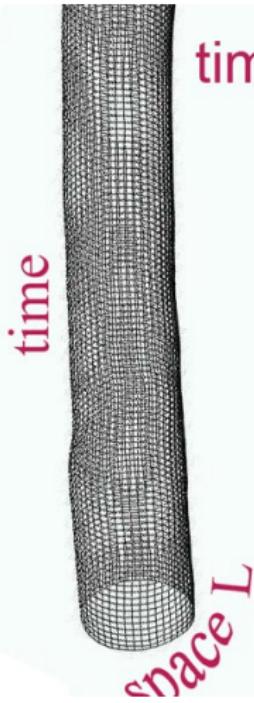


[horizontal] space $x \in [0, L]$ [up] time evolution

- turbulent behavior
- simpler physical, mathematical and computational setting than Navier-Stokes

compact space, infinite time cylinder

time evolution, periodic space



so far : Navier-Stokes on compact spatial domains, all times

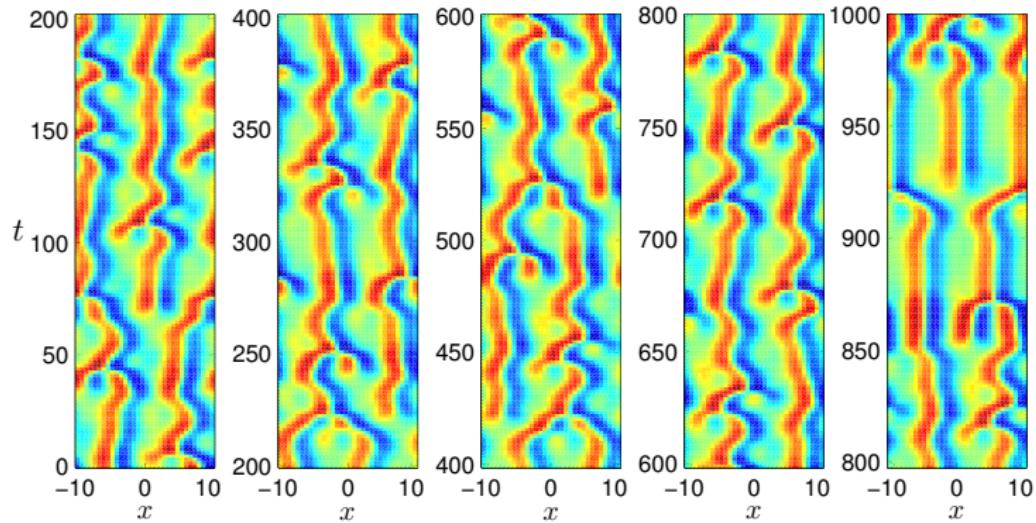
compact space, infinite time Kuramoto-Sivashinsky

in terms of discrete spatial Fourier modes

N ordinary differential equations (ODEs) in time

$$\dot{\tilde{u}}_k(t) = (q_k^2 - q_k^4) \tilde{u}_k(t) - i \frac{q_k}{2} \sum_{k'=0}^{N-1} \tilde{u}_{k'}(t) \tilde{u}_{k-k'}(t).$$

evolution of Kuramoto-Sivashinsky on small $L = 22$ cell



horizontal: $x \in [-11, 11]$

vertical: time

color: magnitude of $u(x, t)$

yes, but

is space time?

compact time, infinite space cylinder

space evolution, periodic time



compact time, infinite space Kuramoto-Sivashinsky¹⁰

$$\begin{aligned} u_t &= -uu_x - u_{xx} - u_{xxxx}, \\ u^{(0)} &\equiv u, \quad u^{(1)} \equiv u_x, \quad u^{(2)} \equiv u_{xx}, \quad u^{(3)} \equiv u_{xxx} \end{aligned}$$

periodic boundary condition in time $u(x, t) = u(x, t + T)$

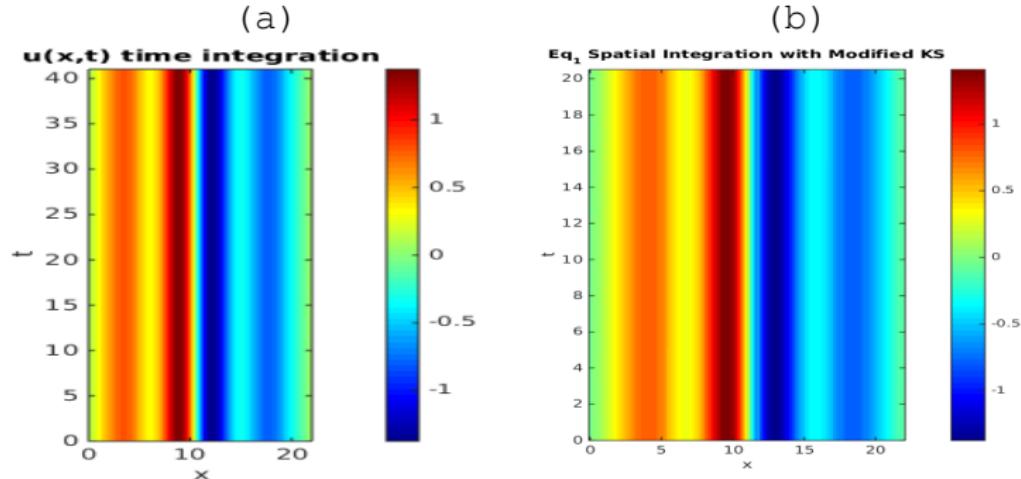
evolve $u(t, x)$ in x , 4 equations, 1st order in spatial derivatives

$$\begin{aligned} u_x^{(0)} &= u^{(1)}, \quad u_x^{(1)} = u^{(2)}, \quad u_x^{(2)} = u^{(3)} \\ u_x^{(3)} &= -u_t^{(0)} - u^{(2)} - u^{(0)}u^{(1)} \end{aligned}$$

initial values $u(x_0, t), u_x(x_0, t), u_{xx}(x_0, t), u_{xxx}(x_0, t)$,
for all $t \in [0, T]$ at a space point x_0

¹⁰M.Gudorf et al., *Is space time? A spatio-temporal theory of transitional turbulence*, In preparation, 2017.

a time-invariant equilibrium, spatial periodic orbit



evolution of EQ_1 : (a) in time, (b) in space

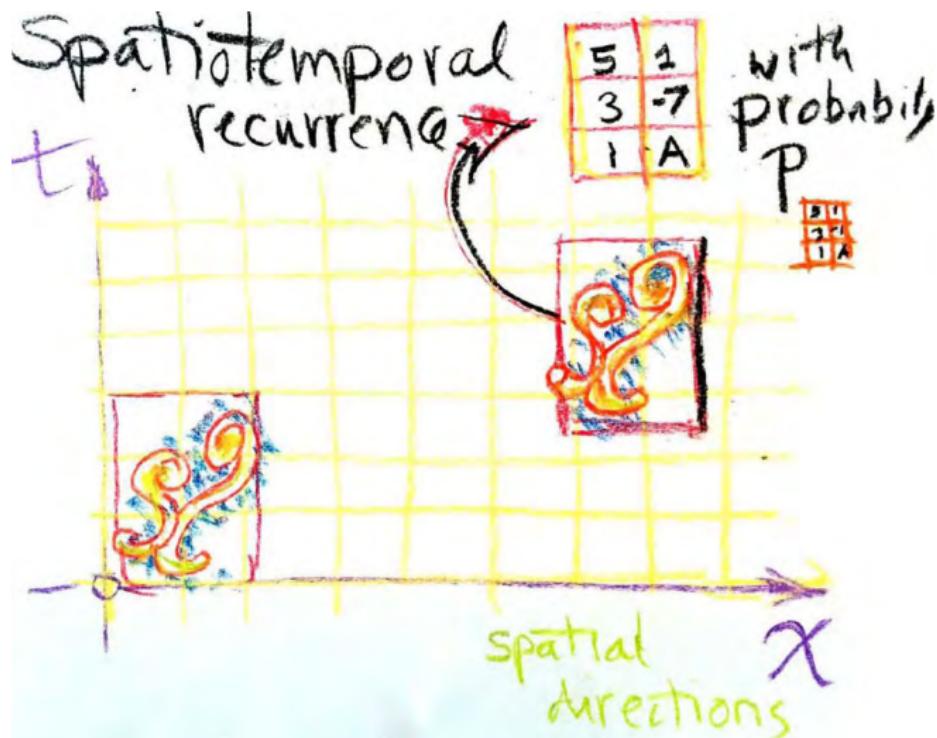
initial condition for the spatial integration is the time strip

$u(x_0, t)$, $t = [0, T]$, where time period $T = 0$, spatial x period is $L = 22$.

Michelson 1986

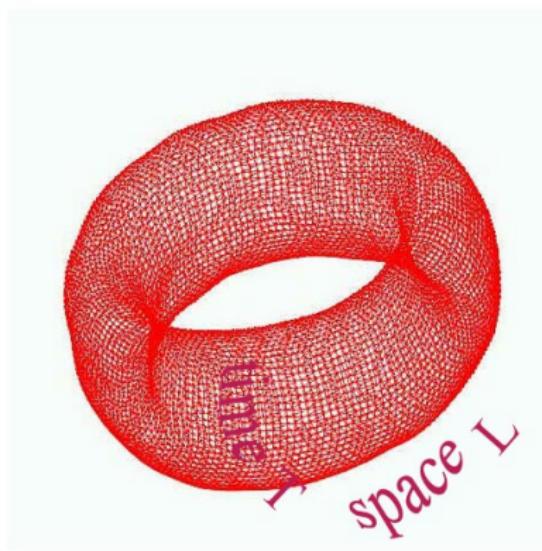
chronotope :

a finite $(1 + D)$ -dimensional symbolic dynamics rectangle



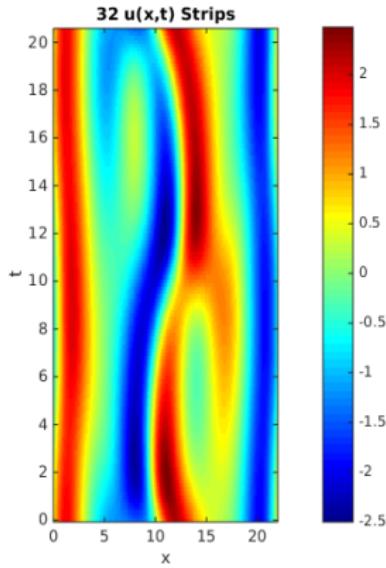
compact space and time chronotope

periodic spacetime : 2-torus

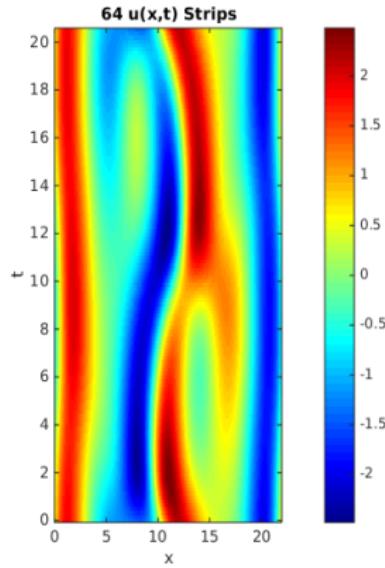


a spacetime invariant 2-torus¹¹

(a)



(b)



(a) old : time evolution.

(b) new : space evolution

$x = [0, L]$ initial condition : time periodic line $t = [0, T]$

Gudorf 2016

¹¹M.Gudorf et al., *Is space time? A spatio-temporal theory of transitional turbulence*, In preparation, 2017.

zeta function for a field theory ? much like Ising model^{12,13}

"periodic orbits" are now spacetime tilings

$$Z(s) \approx \sum_p \frac{e^{-A_p s}}{|\det(1 - J_p)|}$$

count all tori / spacetime tilings : each of area $A_p = L_p T_p$

symbolic dynamics : $(1 + D)$ -dimensional

essential to encoded shadowing

at this time : this zeta is still but a dream

¹²M. Kac and J. C. Ward, Phys. Rev. **88**, 1332–1337 (1952).

¹³Y. Ihara, J. Math. Society of Japan **18**, 219–235 (1966).

conclusion

space, time coordinates merely parametrize a given invariant solution

what matters is

the enumeration of distinct invariant solutions

problem

unable to integrate the equations for times beyond Lyapunov time

unable to integrate the equations for large spatial domains

spatial integration is ill-posed, wildly unstable¹⁴

¹⁴Q. Wang et al., Phys. Fluids **25**, 110818 (2013).

part 4

- ① “turbulence” in small domains
- ② “turbulence” in infinite spatial domains
- ③ space is time
- ④ **bye bye, dynamics**

computing spacetime solutions

A R R I V A L



kiss your DNS codes

goodbye

for long time and/or space integrations

they never worked and could never work

life outside of time

the trouble:

forward time-integration codes too unstable

multishooting inspiration: replace a guess that a point is on the periodic orbit by a guess of the entire orbit.

an example is “Newton descent” : a variational method to drive the initial guess toward the exact solution.

→

a variational method for finding spatio-temporally periodic solutions of classical field theories¹⁵

¹⁵Y. Lan et al., Phys. Rev. E **74**, 046206 (2006).

1d example : variational principle for any periodic orbit^{16,17}

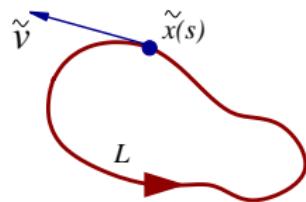
N guess points $\rightarrow \infty$ points along a smooth loop (snapshots of the pattern at successive time instants)

¹⁶Y. Lan and P. Cvitanović, Phys. Rev. E **69**, 016217 (2004).

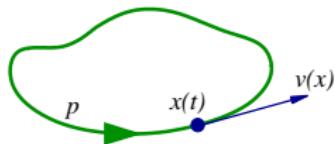
¹⁷P. Cvitanović and Y. Lan, in Correlations and fluctuations in qcd : proceedings of 10th international workshop on multiparticle production, edited by N. Antoniou (2003), pp. 313–325.

a guess loop vs. the desired solution

loop **defines** tangent vector \tilde{v}



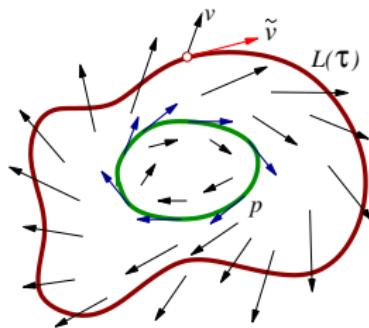
periodic orbit **defined** by
velocity field $v(x)$



extremal principle for a general flow

loop tangent $\tilde{v}(\tilde{x}) \neq v(\tilde{x})$

periodic orbit $\tilde{v}(\tilde{x}), v(\tilde{x})$ aligned



cost function

$$F^2[\tilde{x}] = \oint_L ds (\tilde{v} - v)^2; \quad \tilde{v} = \tilde{v}(\tilde{x}(s, \tau)), \quad v = v(\tilde{x}(s, \tau)),$$

penalizes misorientation of the loop tangent $\tilde{v}(\tilde{x})$ relative to the true dynamical flow $v(\tilde{x})$

Newton descent

cost minimization

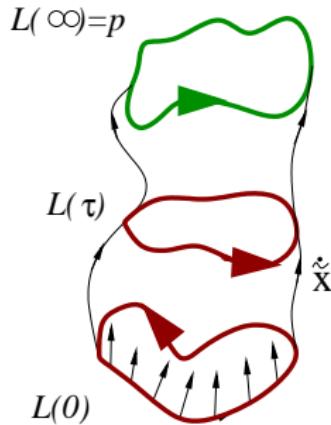
drives

initial guess $L(0)$

\rightarrow

cycle $p = L(\infty)$

as fictitious time $\tau \rightarrow \infty$



the answer is

scalability

in the spirit of this workshop

compute locally, adjust globally

Computing literature : parallelizing **spatiotemporal** computation
is FLOPs intensive, but more robust than integration forward in
time¹⁸

¹⁸Q. Wang et al., Phys. Fluids **25**, 110818 (2013).

how do clouds solve field equations?

do clouds integrate Navier-Stokes equations?



NO!

⇒ other swirls ⇒



at any spacetime point Navier-Stokes equations describe the local tangent space

they satisfy them **locally**, everywhere and at all times

summary

- ① small computational domains reduce “turbulence” to “single particle” chaos
- ② consider instead turbulence in infinite spatiotemporal domains
- ③ theory : classify all spatiotemporal tilings
- ④ numerics : parallelize spatiotemporal computations

there is no more time

there is only enumeration of spacetime solutions

bonus slide : each chronotope is a fixed point

discretize $u_{n,m} = u(x_n, t_m)$ over NM points of spatiotemporal periodic lattice $x_n = nT/N$, $t_m = mT/M$, Fourier transform :

$$\tilde{u}_{k,\ell} = \frac{1}{NM} \sum_{n=0}^{N-1} \sum_{m=0}^{M-1} u_{n,m} e^{-i(q_k x_n + \omega_\ell t_m)}, \quad q_k = \frac{2\pi k}{L}, \quad \omega_\ell = \frac{2\pi \ell}{T}$$

Kuramoto-Sivashinsky is no more a PDE / ODE, but a fixed point problem of determining all invariant unstable 2-tori

$$[-i\omega_\ell - (q_k^2 - q_k^4)] \tilde{u}_{k,\ell} + i \frac{q_k}{2} \sum_{k'=0}^{N-1} \sum_{m'=0}^{M-1} \tilde{u}_{k',m'} \tilde{u}_{k-k',m-m'} = 0$$

Newton method for a NM -dimensional fixed point :
invert $1 - J$,
where J is the 2-torus Jacobian matrix, yet to be elucidated

bonus slide : dynamical zeta function for a field theory

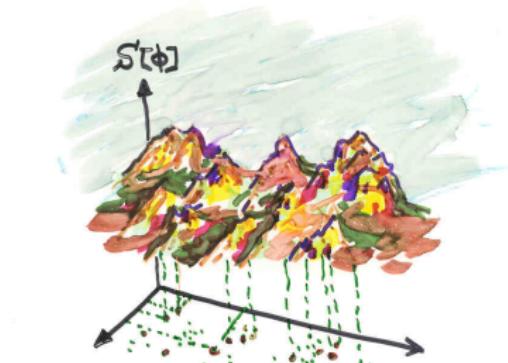
trace formula for a field theory

TURBULENT Q.F.T. ?

∞ of spacetime tilings

$$Z(s) \approx \sum_p \frac{e^{-A_p s}}{|\det(1 - J_p)|}$$

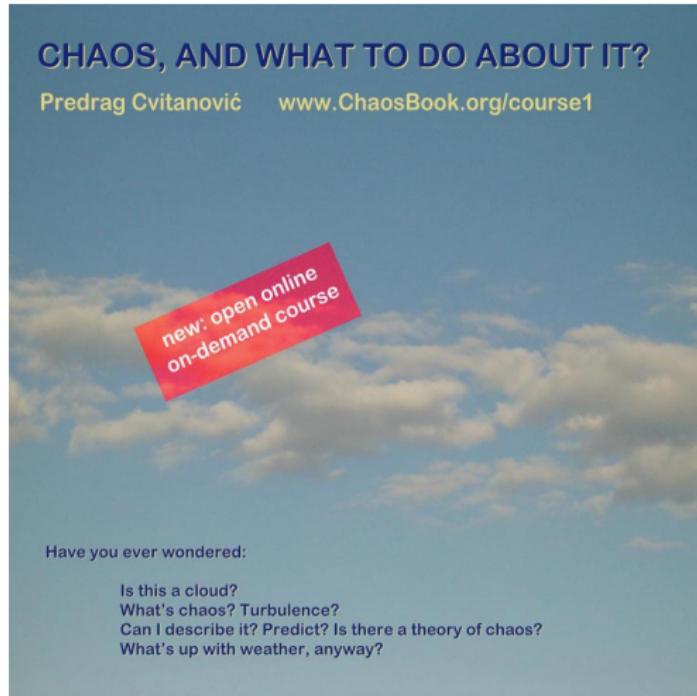
tori / plane tilings
each of area $A_p = L_p T_p$



$$(observable) = \sum_{\text{set}}^{\text{fractal}} \frac{e^{i S_n[\phi_c]/\hbar}}{\sqrt{\frac{\pi^{2S}}{\partial \phi_i \cdot \partial \phi_j}}}$$

learn to
count + weigh unstable saddles

**what is next for the students of Landau's Theoretical Minimum?
take the course!**



The image shows the front cover of a book titled "CHAOS, AND WHAT TO DO ABOUT IT?" by Predrag Cvitanović. The book is set against a background of a blue sky with white clouds. A red, tilted rectangular banner across the middle of the cover contains the text "new: open online on-demand course". Below the banner, the author's name and the website "www.ChaosBook.org/course1" are printed.

Have you ever wondered:

Is this a cloud?
What's chaos? Turbulence?
Can I describe it? Predict? Is there a theory of chaos?
What's up with weather, anyway?

student raves :

... 10^6 times harder than any other online course...

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