International Seminar and Workshop Causality, Information Transfer and Dynamic Networks Max Planck Institute for the Physics of Complex Systems

## Causal Network Inference by Optimal Causation Entropy

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#### **Dynamics on Networks**

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#### Dynamical Processes of Complex Networks

Alain Barrat, Marc Barthélemy, Alessandro Vespign

#### REVIEWS OF MODERN PHYSICS, VOLUME 80, OCTOBER-DECEMBER 2008

#### Critical phenomena in complex networks

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o de Física, Universidade de Aveiro, 3810-193 Aveiro, Portugal October 2008)

on of the compactness of networks, featuring small diameters, and their complex esults in a variety of critical effects dramatically different from those in cooperative ices. In the last few years, important steps have been made toward understanding the w critical phenomena in complex networks. The results, concepts, and methods of this bing field are reviewed. Two closely related classes of these critical phenomena are mely, structural phase transitions in the network architectures and transitions in dels on networks as substrates. Systems where a network and interacting agents on it other are also discussed. A wide range of critical phenomena in equilibrium and orks including the birth of the giant connected component, percolation, k-core enomena near epidemic thresholds, condensation transitions, critical phenomena in perced on networks synchronization and self-organized criticality effects in interacting

Synchronization A universal concept in nonlinear sciences

Arkady Pikovsky, Michael Rosenblum, and Jürgen Kurths



# physicstoday



#### **The Problem of Causal Network Inference**



Given: (time series) observations at each component of a system Goal: identify the *direct* causal relationships between the components

...there are several reasons...

medical diagnosis: identify the causes of a disease in order to suggest effective treatments





#### **Procedure of Causal Network Inference**

Gather a sufficient amount of relevant data (experimental work)

Develop an appropriate causal inference measure (theoretical work)

Accurate and reliable estimate of such a measure (computational/statistical work)

#### A good causal inference measure should satisfy

...general applicability and neat interpretation...

...immune (in principle) to false positives and false negatives...

...accurate and fast numerical estimation...

**Condition** (1)  $\rightarrow$ ...linear and nonlinear interactions...

**Condition** (2)  $\rightarrow$ ...correct identification of direct couplings in complex systems with more than two components...

**Condition** (3)  $\rightarrow$ ...appropriate statistical estimation techniques...

#### **Correlation vs. Causality**



#### **Correlation does not imply causality.**



## Information vs. Physical Causality

Paul the Octopus Google paul the octopus							
1.2							
Paul in his	Opponent +	Tournament +	Stage +	Date +	Prediction +	Result +	Outcome +
	Poland	Euro 2008	group stage	8 June 2008	Germany	2–0	Correct
	Croatia	Euro 2008	group stage	12 June 2008	Germany <sup>[2][21]</sup>	1–2	Incorrect
	Austria	Euro 2008	group stage	16 June 2008	Germany	1–0	Correct
	Portugal	Euro 2008	quarter-finals	19 June 2008	Germany	3–2	Correct
	c. Turkey	Euro 2008	semi-finals	25 June 2008	Germany	3–2	Correct
	Spain	Euro 2008	final	29 June 2008	Germany <sup>[2]</sup>	0–1	Incorrect
	🏭 Australia	World Cup 2010	group stage	13 June 2010	Germany <sup>[30]</sup>	4–0	Correct
Other appellation Species Sex	Serbia	World Cup 2010	group stage	18 June 2010	Serbia <sup>[30]</sup>	0–1	Correct
	Ghana	World Cup 2010	group stage	23 June 2010	Germany <sup>[30]</sup>	1–0	Correct
	- England	World Cup 2010	round of 16	27 June 2010	Germany <sup>[31]</sup>	4–1	Correct
	- Argentina	World Cup 2010	quarter-finals	3 July 2010	Germany <sup>[24]</sup>	4–0	Correct
	s Spain	World Cup 2010	semi-finals	7 July 2010	Spain <sup>[32]</sup>	0–1	Correct
Occupation	💻 Uruguay	World Cup 2010	3rd place play-off	10 July 2010	Germany	3–2	Correct
Known for							

Argentine chef Nicolas Bedorrou was so angry after Paul correctly predicted his team would lose its quarter-final clash with Germany that
 he suggested a way to cook the octopus.

2 days ago - Lucknow. The football world, rendered directionless by the demise of soothsayer **Paul the Octopus**, has found its order back again. And in the ...

### **Mathematical Assumptions**

The necessity of making assumptions:

M. Eichler, Graphical modeling of multivariate time series, Probability Theory and Related Fields (2012).

Stochastic process  $\{X_t^{(i)}\}_{i=1,2,...,N;t=1,2,...}$ (i) Temporally Markov:  $p(X_t|X_{t-1}, X_{t-2}, ...) = p(X_t|X_{t-1}) = p(X_{t'}|X_{t'-1})$  for any t and t'. (ii) Spatially Markov:  $p(X_t^{(i)}|X_{t-1}) = p(X_t^{(i)}|X_{t-1}^{(N_i)})$  for any i. (iii) Identifiability:  $p(X_t^{(i)}|X_{t-1}^{(K)}) \neq p(X_t^{(i)}|X_{t-1}^{(L)})$  whenever  $(K \cap N_i) \neq (L \cap N_i)$ .

 $N_i$  : set of direct causal components of i



#### (also assumes full observability of all the components)

#### **Basic Information-theoretic Measures**

Entropy  $h(X) = -\int p(x)\log p(x)dx$ Joint entropy:  $h(X, Y) \equiv h(Y, X) \equiv -\int p(x, y) \log p(x, y) dx dy.$ Conditional entropies:  $\begin{cases} h(X|Y) \equiv -\int p(x, y) \log p(x|y) dx dy; \\ h(Y|X) \equiv -\int p(x, y) \log p(y|x) dx dy. \end{cases}$ 

Mutual information:  $I(X;Y) \equiv h(X) - h(X|Y) \equiv h(Y) - h(Y|X)$ . Conditional mutual information:

$$I(X;Y|Z) \equiv h(X|Z) - h(X|Y,Z) \equiv h(Y|Z) - h(Y|X,Z).$$



Cover & Thomas (2006).

 $\blacksquare \underset{I(X;Y)=h(X)+h(Y)-h(X,Y)}{\text{mutual information}}$ 

 $\blacksquare \begin{array}{l} \text{mutual information} \\ I(X;Y;Z) = I(X;Y) - I(X;Y|Z) \end{array}$ 

# Transfer Entropy, Self-Causality, and Conditioning **Transfer Entropy (TE)**

$$\Gamma_{Y \to X} \equiv h(X_{t+1} | \mathbf{X}_t) - h(X_{t+1} | \mathbf{X}_t, \mathbf{Y}_t)$$

$$future of X past of X past of Y$$

 $T_{Y \to X}$  measures the reduction of uncertainty about  $X_{t+1}$  given knowledge about  $\mathbf{Y}_t$  in addition to that of  $\mathbf{X}_t$ . T. Schreiber, Phys. Rev. Lett. 85, 461 (2000)

#### A. Kaiser & T. Schreiber, Physica D (2002)

M. Palus et. al., Phys. Rev. E (2001)

#### **Remarks**:

1.  $T_{X \to X} \equiv 0$ , TE makes no indication about whether the process  $\{X_t\}$ is self-causal or not, and is not designed to address such question.

2.  $T_{Y \to X}$  is a bivariate measure (from Y to X), and is therefore not designed to infer direct causality within multiple processes.

# Self-causal or not affects system controllability. Cowan et.al., PLOS ONE (2012)

When there are multiple processes,  $\mathbf{Y}_t$  directly causes  $X_{t+1}$  only if such "cause" remains after the removal of all other conditions.

> Frenzel and Pompe, Phys. Rev. Lett. (2007) Vejmelka and Palus, Phys. Rev. E (2008)

#### **Benjamin Franklin and Clive Granger**



For want of a naíl a shoe was lost, For want of a shoe a horse was lost, For want of a horse a battle was lost

and



**Clive Granger** 

Benjamin Franklin

For want of a battle a kíngdom was lost. And all for the want of a horseshoe naíl.

**Conclusion - The blacksmith destroyed the kingdom.** 

- everything is connected to everything
- everything causes (and is caused by) everything
  ....yes....but not so useful.

Granger's notion of causality: (Granger, 1969)

(1) The cause should occur before the effect (caused)

(2) The causal process should carry information unavailable in other processes—about the effect.

#### **Causation Entropy**

The **Causation Entropy (CSE)** from the set of components **J** to **I** conditioning on **K** is defined (explicitly) as:

$$C_{J \to I|K} = h(X_{t+1}^{(I)}|X_t^{(K)}) - h(X_{t+1}^{(I)}|X_t^{(K)}, X_t^{(J)})$$



#### **Remarks:**

1. CSE can be used to assess whether a process is "self-causal".

2. CSE does not "solve" the causal inference problem.

3. The definition simply emphasizes the fact that cause-and-effect is not a bivariate question, but rather, involves all three parts (*cause*, *effect*, and *conditioning*).

#### **Analytical Properties of CSE**



(a) (Redundancy) If J ⊂ K, then C<sub>J→I|K</sub> = 0.
(b) (No false positive) If N<sub>I</sub> ⊂ K, then C<sub>J→I|K</sub> = 0 for any set of nodes J.
(c) (True positive) If J ⊂ N<sub>I</sub> and J ⊄ K, then C<sub>J→I|K</sub> > 0.
(d) (Decomposition) C<sub>J→I|K</sub> = C<sub>(K∪J)→I</sub> − C<sub>K→I</sub>.

(Optimal Causation Entropy Principle) The set of direct causal neighbors is the minimal set of nodes with maximal Causation Entropy. Define the family of sets with maximal Causation Entropy as

(2.26)  $\mathcal{K} = \{ K | \forall K' \subset \mathcal{V}, C_{K' \to I} \leq C_{K \to I} \}.$ 

Then the set of direct causal neighbors satisfies

$$(2.27) N_I = \cap_{K \in \mathcal{K}} K = \operatorname{argmin}_{K \in \mathcal{K}} K$$

## **Existing Approaches of Conditioning**

**1. Condition on everything:** 



curse of dimensionality
 (estimation in the full dimensional space)

2. Condition on subsets of increasing cardinality (PC-algorithm)

– combinatorial search(high computational burden)

$$\frac{n^2(n-1)^{k-1}}{(k-1)!}$$

Spirtes, Glymour, Scheines (2000). Runge, Heitzig, Petoukhov, Kurths, PRL (2012)

#### Forward & Backward Conditioning: Discover & Remove



#### **Remarks:**

1. The "forward" step (Aggregative Discovery) alone in principle would result in false positives that cannot be mitigated by the increased amount of data. Vlachos, Kugiumtzis, Phys. Rev. E (2010); Kugiumtzis, Phys. Rev. E (2013)

2. The "backward" step (Divisive removal) can be modified to one that is analogous to the PC-algorithm in the statistical inference literature, with the key difference that here enumeration of conditioning subsets needs to be performed only within K, rather than for all nodes. Spirtes, Glymour, Scheines (2000). Runge, Heitzig, Petoukhov, Kurths, PRL (2012)

#### **Benchmark Systems**

 $X_t^{(i)} = \sum_{j \in N_i} A_{ij} X_{t-1}^{(j)} + \xi_t^{(i)} - Classical \ communication \ channel - Fluctuations \ around \ equilibrium$ 

stable adjacency matrix

uncorrelated Gaussian noise

Ahmed and Gokhale, IEEE Trans. Info. Theor. (1989). Barnett, Phys. Rev. Lett. (2009).

 $X_t^{(i)} \text{ are Gaussian, with covariance } \Phi(\tau, t)_{ij} \equiv \operatorname{cov}[x_{t+\tau}^{(i)}, x_t^{(j)}] \\ \begin{cases} \Phi(0) \equiv \lim_{t \to \infty} \Phi(0, t) = \sum_{k=0}^{\infty} A^k S(A^k)^\top \\ \Phi(\tau) = A \Phi(\tau - 1) = A^2 \Phi(\tau - 2) = \dots = A^\tau \Phi(0) \end{cases}$  $C_{J \to I|K} = \frac{1}{2} \log \left( \frac{\det \left[ \Phi(0)_{II} - \Phi(1)_{IK} \Phi(0)_{KK}^{-1} \Phi(1)_{IK}^{\top} \right]}{\det \left[ \Phi(0)_{II} - \Phi(1)_{I,K \cup J} \Phi(0)_{K \cup J,K \cup J}^{-1} \Phi(1)_{I,K \cup J}^{\top} \right]} \right)$ 

#### **Analytical Calculation: Directed Linear Chain**



#### **Analytical Calculation: Directed Loop**





#### **Analytical Calculation: Directed Tree**



No conditioning:  $C_{j \to i} = \frac{1}{2} \delta_{d_i, d_j + 1} \log \frac{(d_i + 1)(d_j + 1)}{(d_i + 1)(d_j + 1) - (d_{p_{ij}} + 1)^2}$ With conditioning:  $\begin{cases} p_i = \arg \max_j C_{j \to i}, \\ C_{j \to i | \{p_i\}} = 0. \end{cases}$ 

#### **Numerical Tests for Random Directed Networks**



#### **Significance Level and Network Size**



#### **Effects of Sample Size and Spectral Radius**



### Conclusions

 oCSE allows for direct causal inference in an efficient way (it can be extended to finite-order Markov process and also process with infinite but fading memory)
 Tradeoff between computation (choosing the conditioning set) and estimation (resulting dimensionality of the random variables)

#### Challenges

- Exact statistical test Pethel and Hahs, Entropy (2014, to appear)

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#### References

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## Thank you!