Pattern Formation in Model Active Systems

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Introduction

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patterns in granular systems

in vitro cytoskeletal networks

suspensions of swimmers

Tomorrow: simple kinetic theory for inelastic rods, application to microtubules/motors systems

Then: models of collective swimming, viscosity reduction

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Where in the World is Argonne?







World-Class Science Unique Scientific Facilities Free and Abundant Parking 25 min from Downtown Chicago White Deer

Energy Sciences Building Stephen Chu



Collective Behavior in Living and Inanimate Matter simple interactions – complex emergent behavior

different mechanisms – similar patterns



Vicsek Model: A Major Theoretical Milestone

Point particles (*boids*) move off-lattice

Driven overdamped (no inertia effects) dynamics

Strictly local interaction range

Alignment according to average direction of the neighbors

Simple update algorithm for the position/orientation of particles Not necessarily reproduce observed phenomenology

1. Polar orienting interaction in a noisy environment

2. Streaming: motion along the polar direction -

More complicated continuum hydrodynamic models (Tu, Toner, Ramaswamy)

Simulations of Vicsek model

Chate and Gregoire, PRL 2004

1,000,000 boids

at large size, discontinuous transition

(similar to magnetization)

Order parameter:





Fundamental Issues (Physicist Point of View)

Similarity between collective behaviors in living and inanimate systems

Role of long-range interactions vs short-range collisions

Derivation of mathematical models from simple interaction rules

<u>Relation between collective behavior and the mechanisms of self-</u> propulsion

Modeling of emergent collective behavior in the lab

Applications for dynamic self-assembly/materials design

Active Systems are <u>Very Complex</u>

Focus on simple yet non-trivial systems such as in vivo cytoskeletal networks, bacterial suspensions

Fundamental interactions are simple and well-characterized

Interactions are mostly of the "physical nature": inelastic collisions, self-propulsion, hydrodynamic entrainment, vs chemotaxis, signaling etc

Derive continuum description from elementary interaction roles and connect observed patterns with experiment

Approach is mesoscopic and is complementary _

Direct simulations of complex systems

Concept of Active Gels (extension of liquid crystal theory to active systems near thermodynamic equilibrium) by Prost, Joanny, Kruse, Julicher

Phenomenological theory by John Toner, Sriram Ramaswamy, Yuhai Tu US DOE Materials Science and Engineering, Biomolecular Program

<u>Major thrust areas</u>: understanding, controlling, and building complex hierarchical structures by <u>mimicking nature's self- and directed-assembly</u> <u>approaches</u>

<u>design and synthesis of environmentally adaptive,</u> <u>self-healing systems</u>

http://science.energy.gov/bes/mse/research-areas/biomolecular-mate

Active Systems – A Unique Opportunity for Materials Science

Design of active self-assembled structures with functionality not available under equilibrium conditions

self-assembled colloidal robot





Blair-Neicu-Kudrolli experiment

top view

vibration of long rods





long Cu cylinders # of particles 104



Phase transitions and vortices



Long-Term Evolution



Origin of Motion

Experiment

Simulations





D Volfson, L Tsimring, A. Kudrolli

es

Swarming in Quasi-2D Experiments

Experiment, 500 asymmetric rods



Simulations, 500 rods



Lumay, D Volfson, L Tsimring, A. Kudrolli PRL 2008

Vibrated Polar Disks

Experiment, 1000 asymmetric disks

re-injecting boundary conditions



Deseigne, Dauchot, Chate, PRL 2010

Recruiting Nanofabrication: micron-size AuPt rods swim in H2O2



AuPt & AuRu microrods are provided by Ayusman Sen and Tom Mallouk, PSU Movie: Argonne





V Schaller et al. Nature 467, 73-77 (2010)

Moving Clusters and Swirls

moderate density

higher density

cluster movement

video1 - supplement to Fig. 2A

filament density: $\rho = 5.5 \,\mu m^{-2}$ labeling ratio: R = 1:200



swirling motion II

video4 - supplement to Fig. 3D

filament density: $\rho = 20 \ \mu m^{-2}$ labeling ratio: R = 1.320



V Schaller et al. Nature 467, 73-77 (2010)

in-vitro Self-Assembly of MT and MM

- ^s Simplified system with only few purified components
- Experiments performed in 2D glass container: diameter 100 μm, height 5μm
- **s** Controlled tubulin/motor concentrations and fixed temperature
- s MT have fixed length 5µm due to fixation by taxol



Patterns in MM-MT mixtures

Formation of asters, large kinesin concentration (scale 100 m)



Vortex – Aster Transitions



Ncd – gluththione-S-transferase-nonclaret disjunctional fusion protein Ncd walks in opposite direction to kinesin²⁵

Dynamics of Aster/Vortex Formation

Kinesin

Ncd



Rotating Vortex

Kinesin



Summary of Experimental Results

2D mixture of MM & MT exhibits pattern formation Kinesin: vortices for low density of MM and asters for higher density Ncd: only asters are observed for all MM densities For very high MM density asters disappear and bundles are formed

Self-Propelled BioParticles

swimming aerobic bacteria Bacillus Subtilis length 5 μ m, speed 20 μ m/sec, Re=10-4 collective flows up to 100 μ m/sec need Oxygen (oxygentaxis)





Turner, Ryu, and Berg (E. coli) ²⁹

Swimming Algae

Eukaryotic Clamydomonas reinhardtii Size: 10 mm, two flagella ~10 mm Swimming speed: 50-100 mm/sec Highly asocial animals

Single Alga



Algae Suspension



Bacillus subtilis primary behaviors



Excellent swimmers No tumbling



Concentration of bacteria near the surface due to gradient of dissolved Oxygen

Bacterial Turbulence



Goldstein, Kessler, et al PRL 2004

Schematics of Experimental Setup



Thin free-standing film concept Adjustable thickness 33 Adjustable concentration of bacteria

pH-Taxis & concentration of cells



pH indicator (bromothynol blue) was added

field of view

concentration vs. time





Bacterial Turbulence



Sokolov, Goldstein, Kessler, I.A PRL (2007)

7-fold reduction of viscosity

vortex probe micro-rheometer

rotational micro-rheometer





viscosity is extracted from the vortex decay time viscosity is extracted from the magnetic torque viscosity vs concentration and swimming speed of bacteria

Sokolov & I.A, <u>PRL 2009</u>

n, 10^{10} cm^{-3}

5

0 0.8

0.4

0.2

Mixing and self-diffusivity in bacterial suspensions Optical coherence tomography





3D concentration distribution



collective swimming enhances mixing by a factor of 10 confinement reduces mixing rates nontrivial 3D patterns result in enhanced transport

Sokolov, Feldstein, Goldstein, I.A, PRE 2009

Machines Powered by Bacteria: Rectification of Chaotic Motion Sokolov, Apodaca, Grzybowski, I.A, <u>PNAS, December 2009</u>

Lithographic Mask

Size of gears: 350 µm, SU-8 photoresist Photolithography technique

Mass of Gear ~106 mass of bacteria

Collaboration with Bartosz Grzybowski, Northwestern University

Featured in NY Times, Forbes, Wired, WDR, Sci American



Gears Turned by Bacteria

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- Third level
 - Fourth level
 - Fifth level

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1 mm

1-2 rotations per minute Power about 1 femtowatt=10-15 Watt About 300 bacteria power the gear

Control of Rotation



Rotation rate vs concentration



Rotation rate controlled by Oxygen/Nitrogen Rotation rate depends on concentration Rotation enhanced by collective swimming

Ratchet Mechanism of Rotation

Trajectory of fluorescent tracers



Bacteria slide along slanted edges Trapped in junctions formed by the teeth Consistent with simulations by Angelini et al, PRL 2008