

LYAPUNOV-LIKE VECTORS FOR ENSEMBLE FORECAST (SPATIO-TEMPORAL MVL ANALYSIS)

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ENSEMBLE FORECASTING

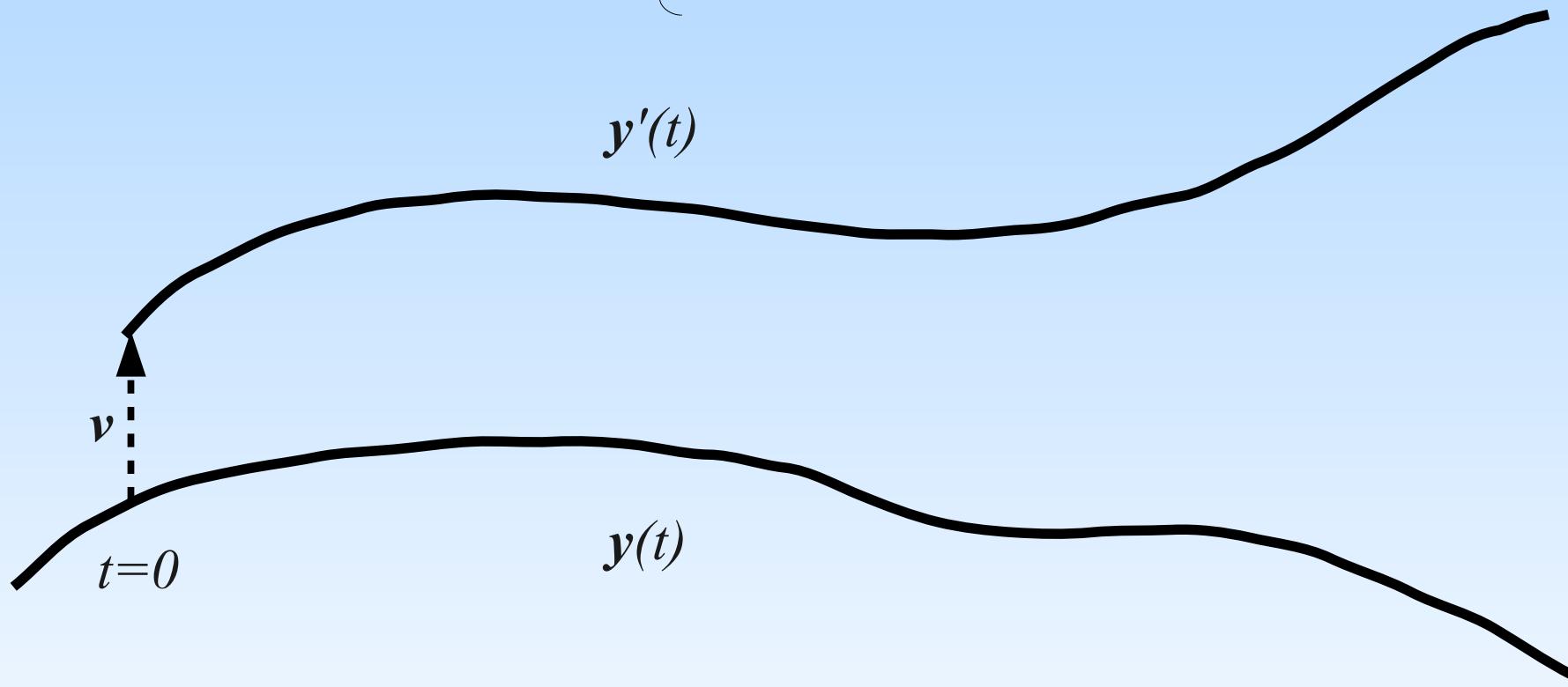
Leith (1974): Ensemble mean outperforms deterministic forecasting.

- Hypothesis:
- Imperfect model (Canada)
 - Perfect model: **dynamic vectors**
 - Bred vectors (USA)
 - Singular vectors (Europe)

- What do we know about the evolution of perturbations initialized along dynamic vectors in **simple** spatio-temporal systems?
- How do their spatial structures evolve?

SPATIO-TEMPORAL EVOLUTION OF AN ENSEMBLE MEMBER

Initialization $\begin{cases} \mathbf{y}'(t=0) = \mathbf{y}(t=0) + \mathbf{v} \\ \mathbf{v} \propto \text{Lyapunov-like vector} \\ \|\mathbf{v}\| \ll 1 \end{cases}$



Spatio-temporal evolution of the finite perturbation $v(t) = y'(t) - y(t)$????

“LYAPUNOV-LIKE” (BRED, LYAPUNOV, SINGULAR) VECTORS FUNDAMENTALS

Finite vectors:

Bred vectors

$$t_m = mT$$

$$\mathbf{l}(t_m) = \mathbf{y}'(t_m) - \mathbf{y}(t_m)$$

$$\mathbf{y}'(t_m) = \mathbf{y}(t_m) + \epsilon_0 \frac{\mathbf{l}(t_m)}{\|\mathbf{l}(t_m)\|}$$

;

$$\|\mathbf{l}\| = \left(\prod_{x=1}^L l_x \right)^{1/L}$$

Geometric mean
“Log-BVs”

Infinitesimal vectors:

Infinitesimal perturbations evolve linearly: $\delta \mathbf{u}(t+\tau) = \mathbf{A}(t+\tau, t) \delta \mathbf{u}(t)$

- Backward Lyapunov vectors: byproduct of Gram-Schmidt method (past growth).
- Forward Lyapunov vectors: future growth.
- Characteristic Lyapunov vectors: covariant with the linear dynamics.
- Singular vectors: perturbation that will exhibit maximal amplification after τ .

“LYAPUNOV-LIKE” (BRED, LYAPUNOV, SINGULAR) VECTORS FUNDAMENTALS

	Vector type	Notation	Magnitude	Computation interval	Eigenvector of	Control parameter(s)
Bred	Log-BV	\mathbf{l}_{M_0}	Finite	$(-\infty, 0)$	—	$M_0 = \ln(\epsilon_0)$
	B-LV	\mathbf{b}_n	Infinitesimal	$(-\infty, 0)$	$\mathbf{A}(0, -\infty)\mathbf{A}^*(0, -\infty)$	n (\leftrightarrow n -th LE)
	F-LV	\mathbf{f}_n	Infinitesimal	$(0, \infty)$	$\mathbf{A}^*(\infty, 0)\mathbf{A}(\infty, 0)$	n (\leftrightarrow n -th LE)
	C-LV	\mathbf{g}_n	Infinitesimal	$(-\infty, 0) \cup (0, \infty)$	—	n (\leftrightarrow n -th LE)
Singular	SV	\mathbf{s}_τ	Infinitesimal	$(0, \tau)$	$\mathbf{A}^*(\tau, 0)\mathbf{A}(\tau, 0)$	τ (here $n = 1$ only)

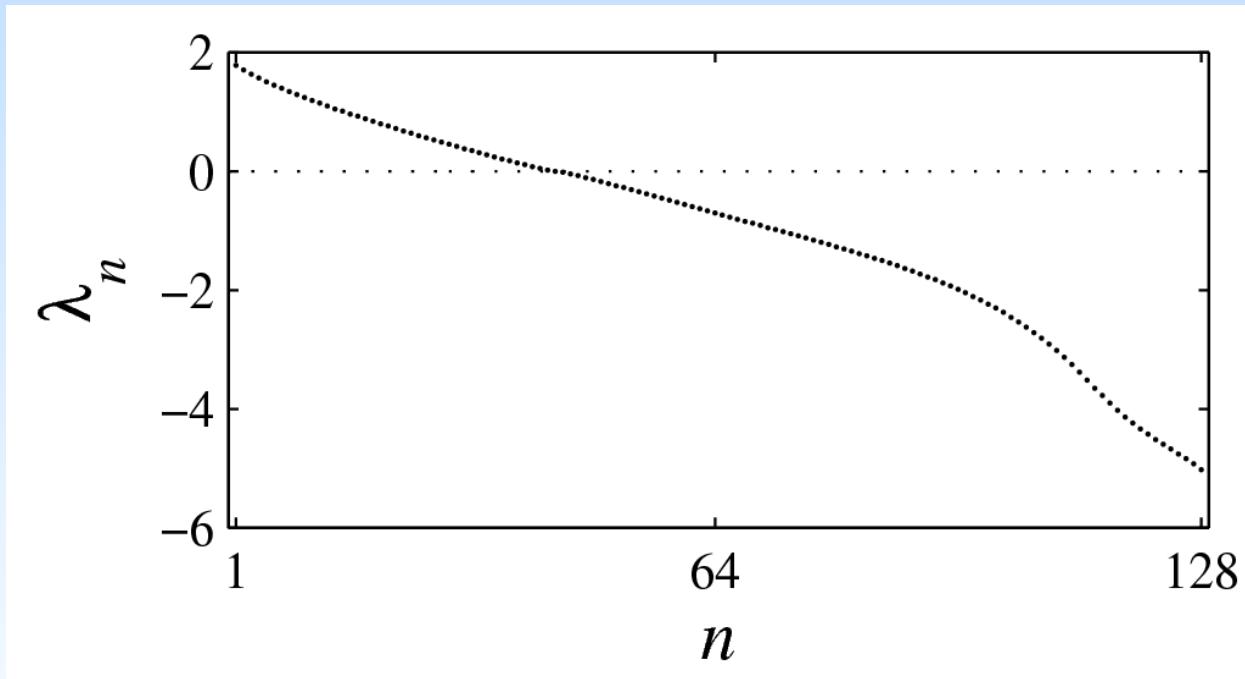
Characteristic-LVs are:

- Independent of the scalar product.
- Covariant with the *linear dynamics*: $\mathbf{g}_n(t+\tau) = \mathbf{A}(t+\tau, t)\mathbf{g}_n(t)$
- Expanding/shrinking with corresponding LE: $\lambda_n = \lim_{\tau \rightarrow \pm\infty} \frac{1}{|\tau|} \|\mathbf{A}(\tau, t)\mathbf{g}_n(t)\|$

SPATIO-TEMPORAL CHAOTIC SYSTEM: LORENZ '96 MODEL

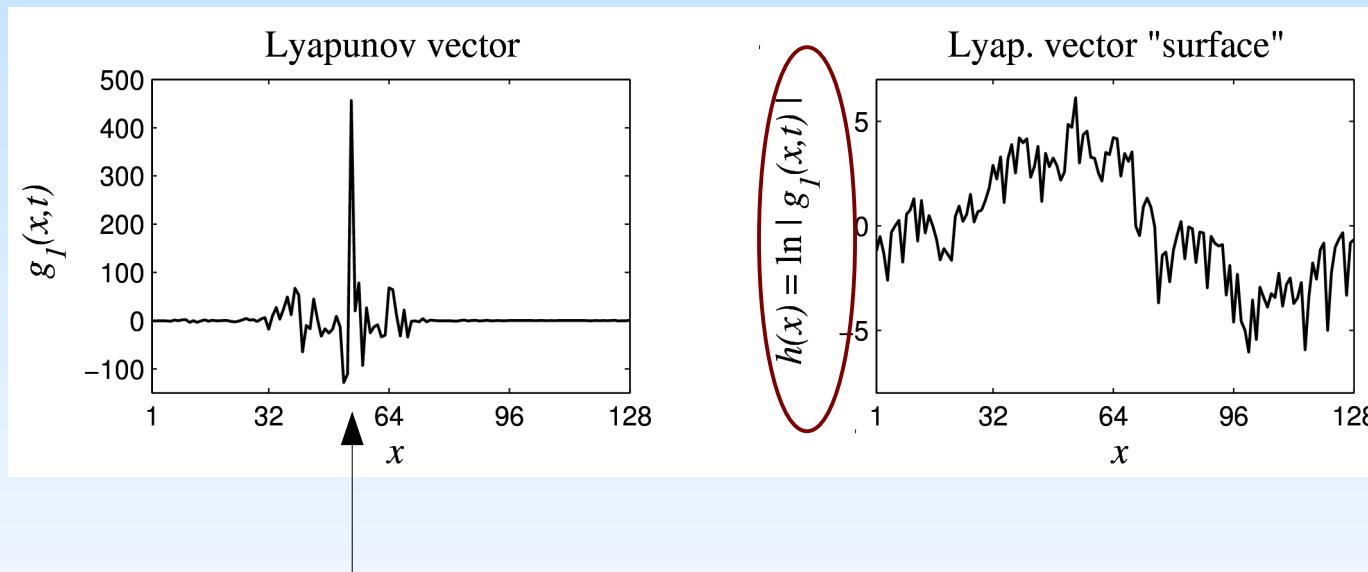
$$\frac{d y_x}{dt} = -y_x - y_{x-1} (y_{x-2} - y_{x+1}) + F \quad x = 1, \dots, L = 128$$

Lyapunov spectrum ($F=8$):



THEORETICAL FRAMEWORK I (Pikovsky and Politi, 1998) : INFINITESIMAL PERTURBATION

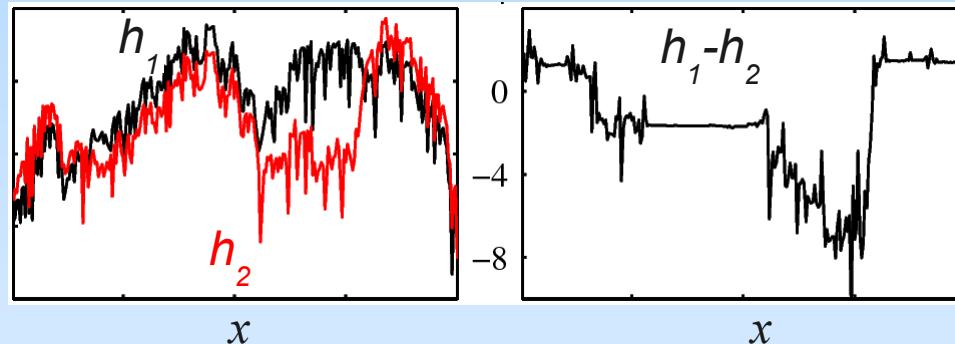
- An infinitesimal perturbation exhibits dynamical localization.
- In log scale it belongs to the universality class of the Kardar-Parisi-Zhang (KPZ) equation [$\partial_t h = \xi + \nabla^2 h + (\nabla h)^2$].



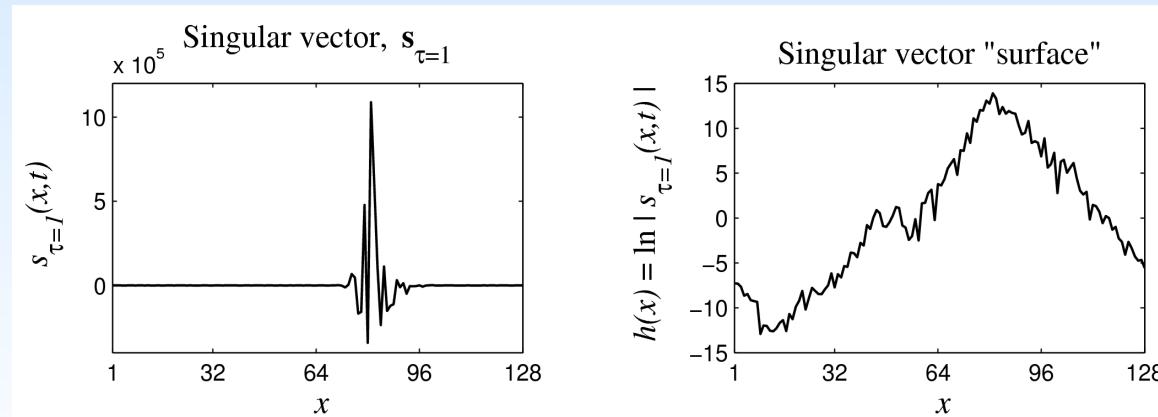
stretched-exponential localization: $|g_1(x)| \sim e^{-k\sqrt{|x-x_0|}}$

THEORETICAL FRAMEWORK II: LYAPUNOV-LIKE VECTORS

- López et al (2004), Primo et al. (2005,2006): Finite perturbations and **bred vectors** (uncorrelation at long scales).
- Szendro et al. (2007), Pazó et al. (2008): **Lyapunov vectors** are “piecewise” copies of the first Lyapunov vector.

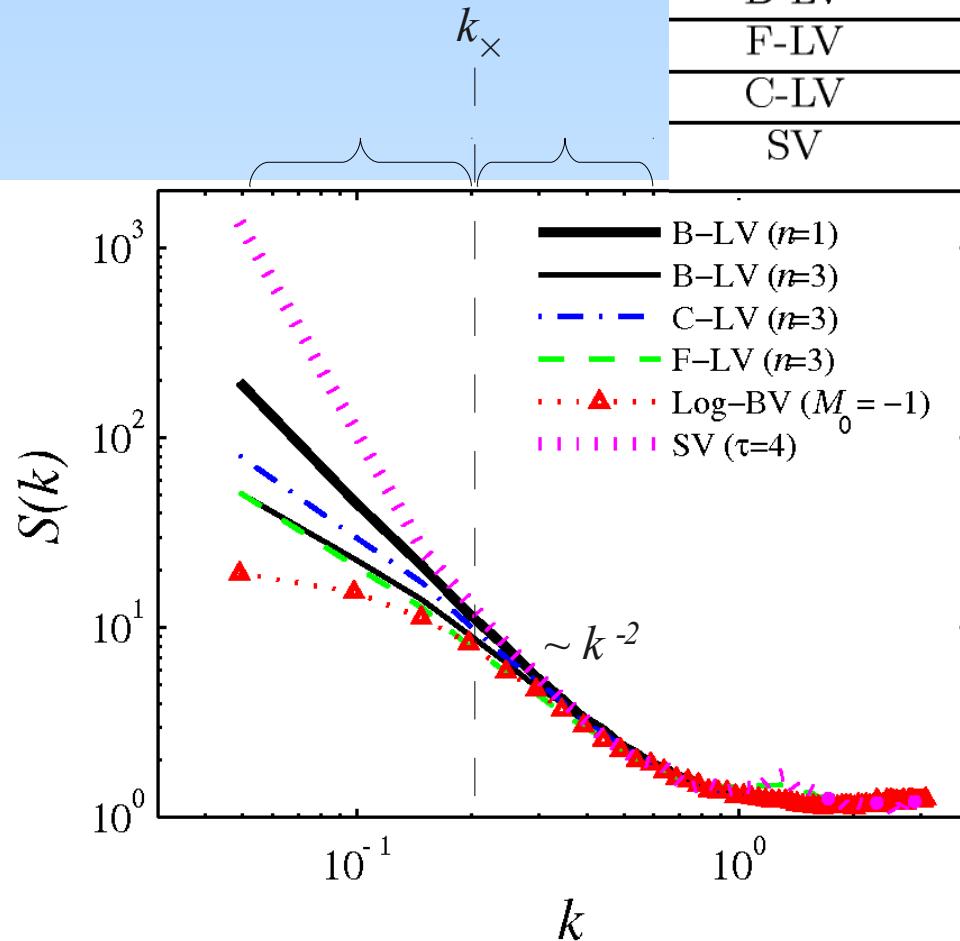


- Pazó et al. (2009): **Singular vectors** are exponentially localized and scale as KPZ with periodic/quenched noise.



SPATIAL POWER SPECTRAL DENSITY

Vector type	Cross. length $l_x = \frac{2\pi}{k_x}$	$S(k < k_x)$	$S(k > k_x)$
Log-BV	$\sim M_0^2$	Constant	
B-LV	$\approx (L/n)^\theta (\theta \approx 1)$	k^{-1}	
F-LV	$\approx (L/n)^\theta (\theta \approx 1)$	k^{-1}	k^{-2}
C-LV	$\approx (L/n)^\theta (\theta \approx 1)$	$k^{-1.15}$	
SV	$\sim \tau^{\gamma/2} (\gamma \simeq 0.78)$	k^{-4}	



Parameters control k_x !!!

QUANTIFICATION OF LOCALIZATION STRENGTH AND Crossover LENGTH: the variance V

Surface picture: $h(x, t) = \ln|v(x, t)|$

$$V(t) = \frac{1}{L} \sum_{x=1}^L h(x, t)^2 - \left(\frac{1}{L} \sum_{x=1}^L h(x, t) \right)^2 \quad \longleftrightarrow \quad \text{Parseval's identity} \quad V = \int S(k) dk$$

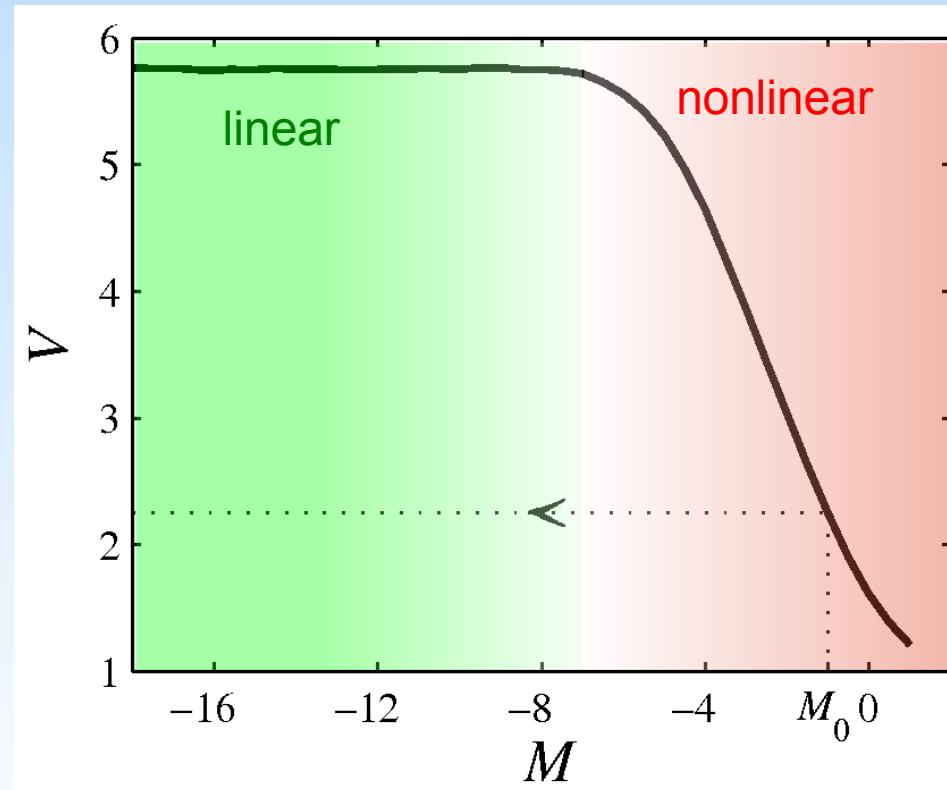
Vector type	Cross. length $l_x = \frac{2\pi}{k_x}$	$S(k < k_x)$	$S(k > k_x)$
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QUANTIFICATION OF AMPLITUDE (finite perturbations): the mean M

$$M(t) = \frac{1}{L} \sum_{x=1}^L h(x, t) \quad (\text{logarithm of the geometric norm})$$

Fixing the perturbation's norm, say $M=M_0$, one obtains the logarithmic bred vectors.

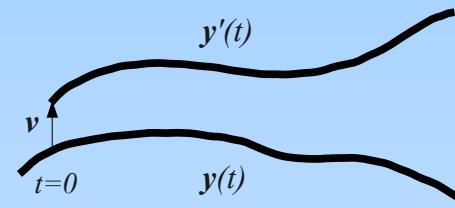
$$\mathbf{l}_{M_0 \rightarrow -\infty} \propto \mathbf{b}_1 = \mathbf{g}_1$$



GROWTH OF FINITE PERTURBATIONS

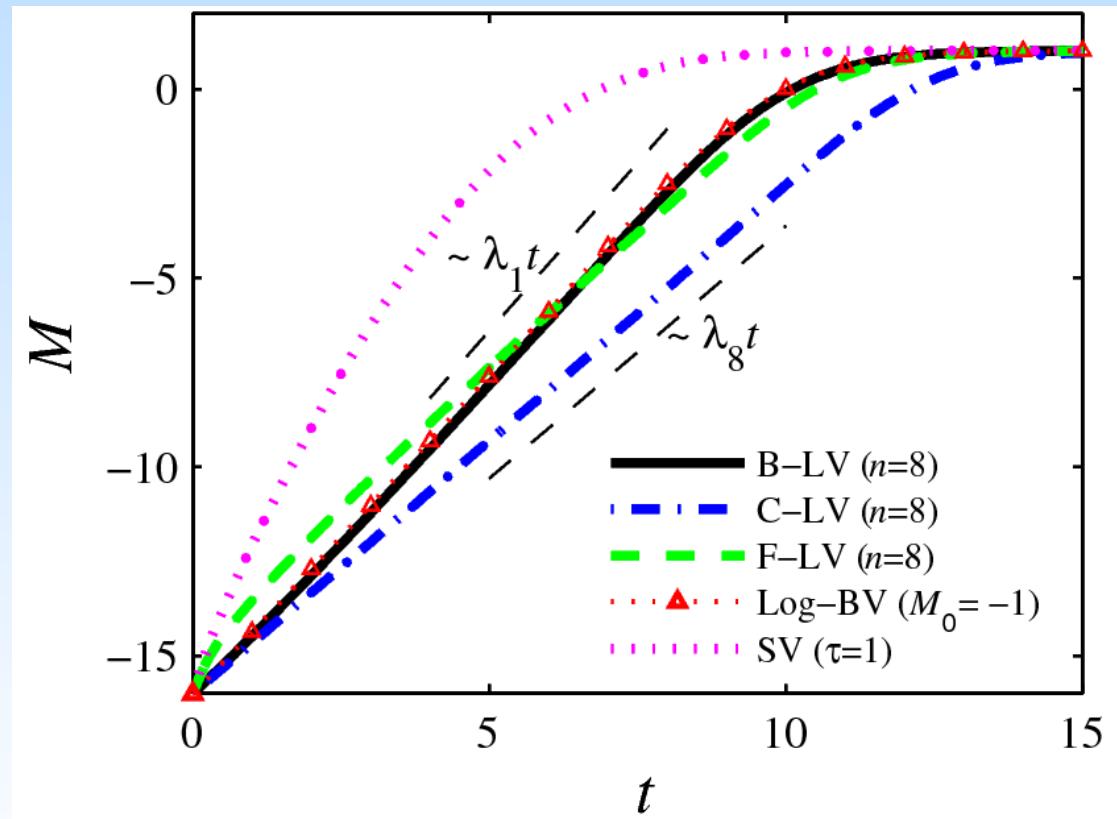
Initialization

$$\begin{cases} y'(t=0) = y(t=0) + v \\ v \propto \{l_{M_0}, b_n, f_n, g_n, s_\tau\} \\ \ln \|v\| = M(t=0) = -16 \end{cases}$$



$$v(t) = y'(t) - y(t)$$

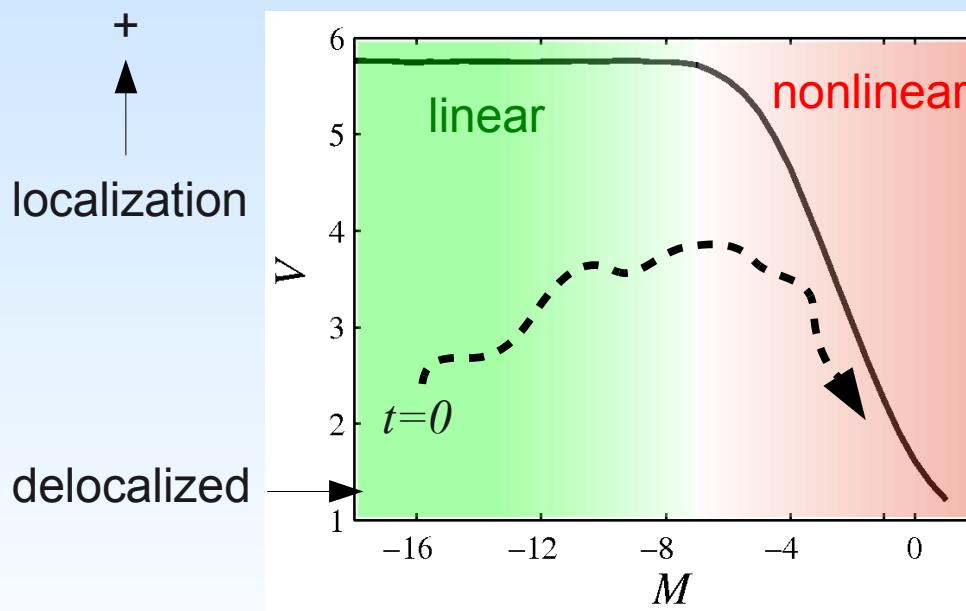
$$M(t) = \frac{1}{L} \sum_{x=1}^L \ln |v(x, t)|$$



SPATIO-TEMPORAL EVOLUTION OF PERTURBATIONS

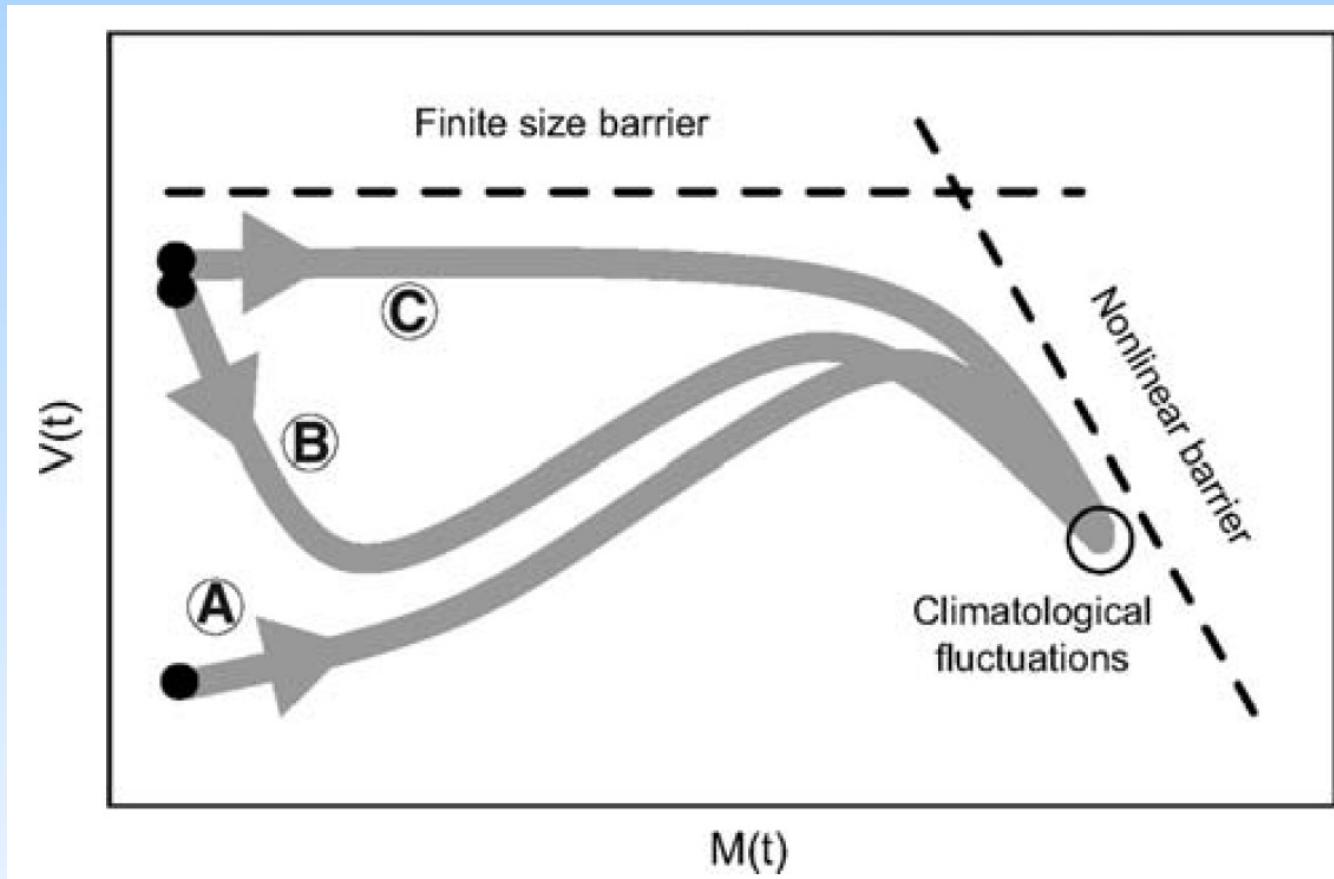
Initialization $\left\{ \begin{array}{l} \mathbf{y}'(t=0) = \mathbf{y}(t=0) + \mathbf{v} \\ \mathbf{v} \propto \{l_{M_0}, b_n, f_n, g_n, s_\tau\} \\ \ln \|\mathbf{v}\| = M(t=0) = -16 \\ V(t=0) \text{ is intrinsic to the selected vector.} \end{array} \right.$

We track $\mathbf{v}(t) = \mathbf{y}'(t) - \mathbf{y}(t)$ in M, V coordinates



MVL (Mean-Variance of Logarithms) DIAGRAM

Introduced by Primo et al. in Phys. Rev. E (2005) and Phys. Rev. Lett. (2007)

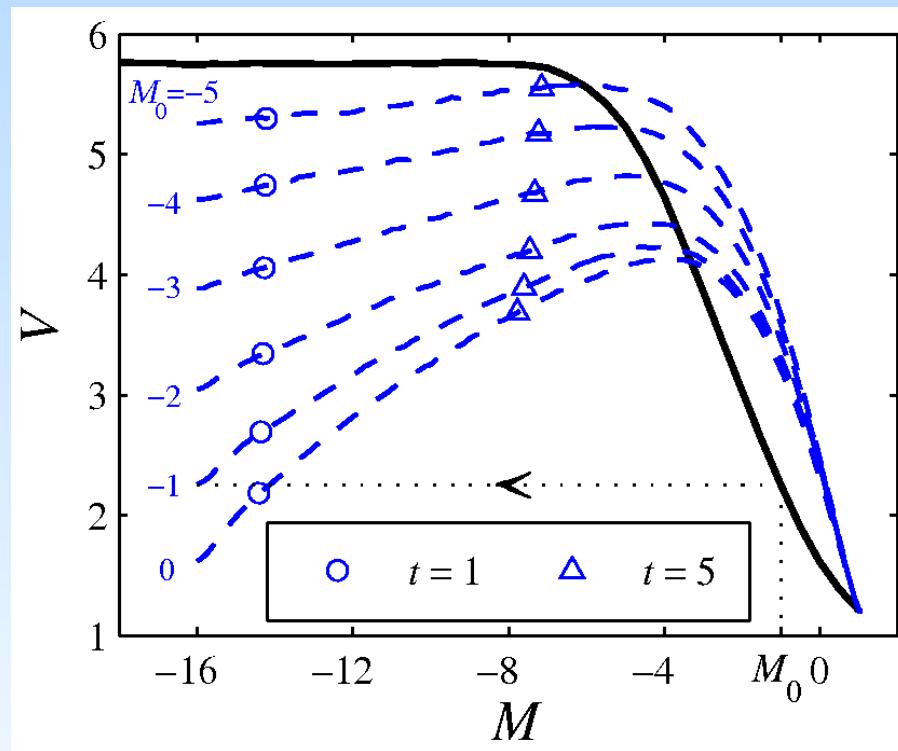


- J.M. Gutiérrez et al., Spatiotemporal characterization of ensemble prediction systems: the mean-variance of logarithms (MVL) diagram, Nonlin. Processes Geophys. (2008).
- J. Fernández et al., MVL spatiotemporal analysis for model intercomparison in EPS: application to the DEMETER multimodel ensemble. Clim. Dyn. (2009).

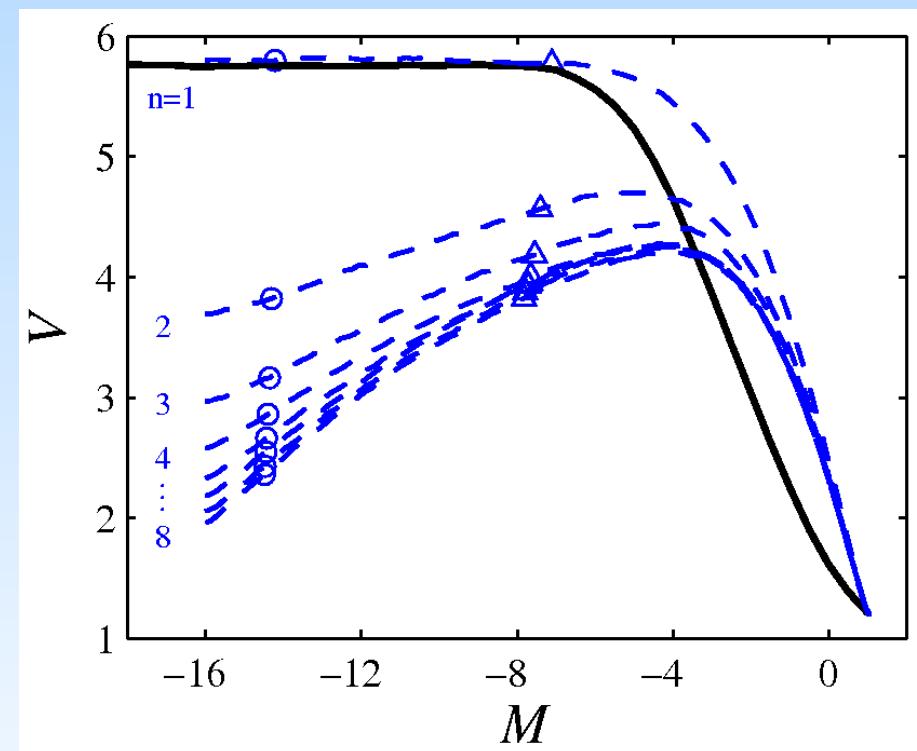
RESULTS

1. Vectors generated from the past are well adapted (and exhibit similar behaviour). Exponential growth rate $\approx \lambda_1$

$\mathbf{v}(0) \propto$ Logarithmic bred vector



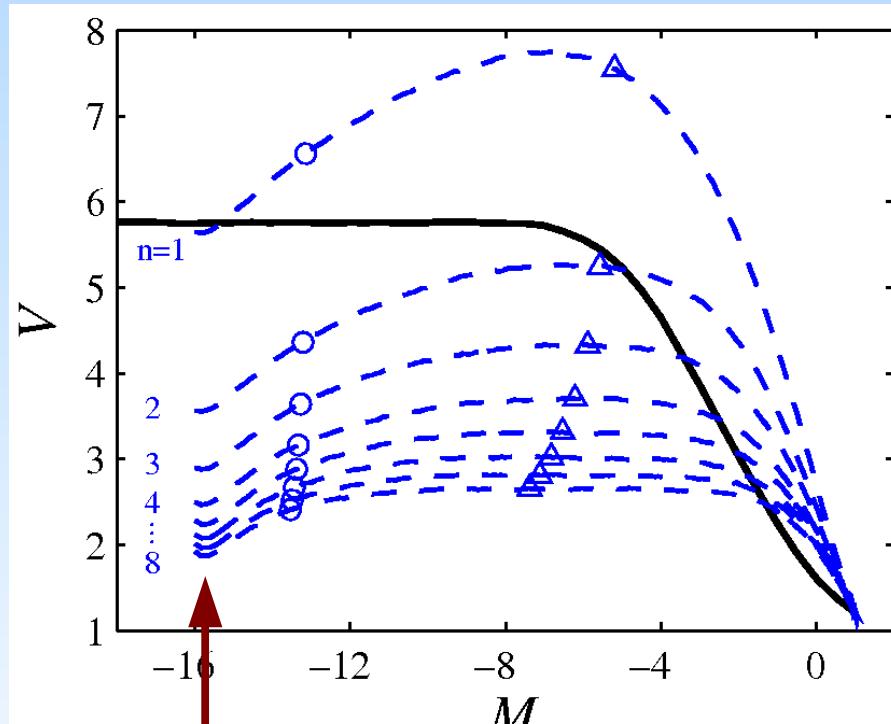
$\mathbf{v}(0) \propto$ Backward Lyapunov vector



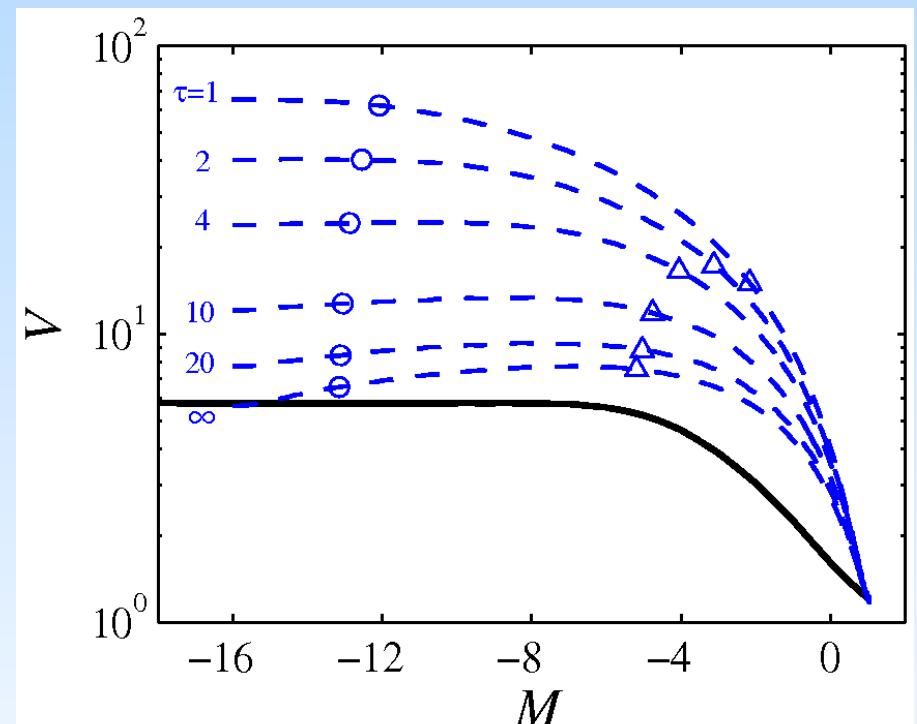
RESULTS

2. Vectors generated from the future are not in the attractor (and exhibit severe transients). Exponential growth rate $\neq \lambda_1$

$v(0) \propto$ Forward Lyapunov vector



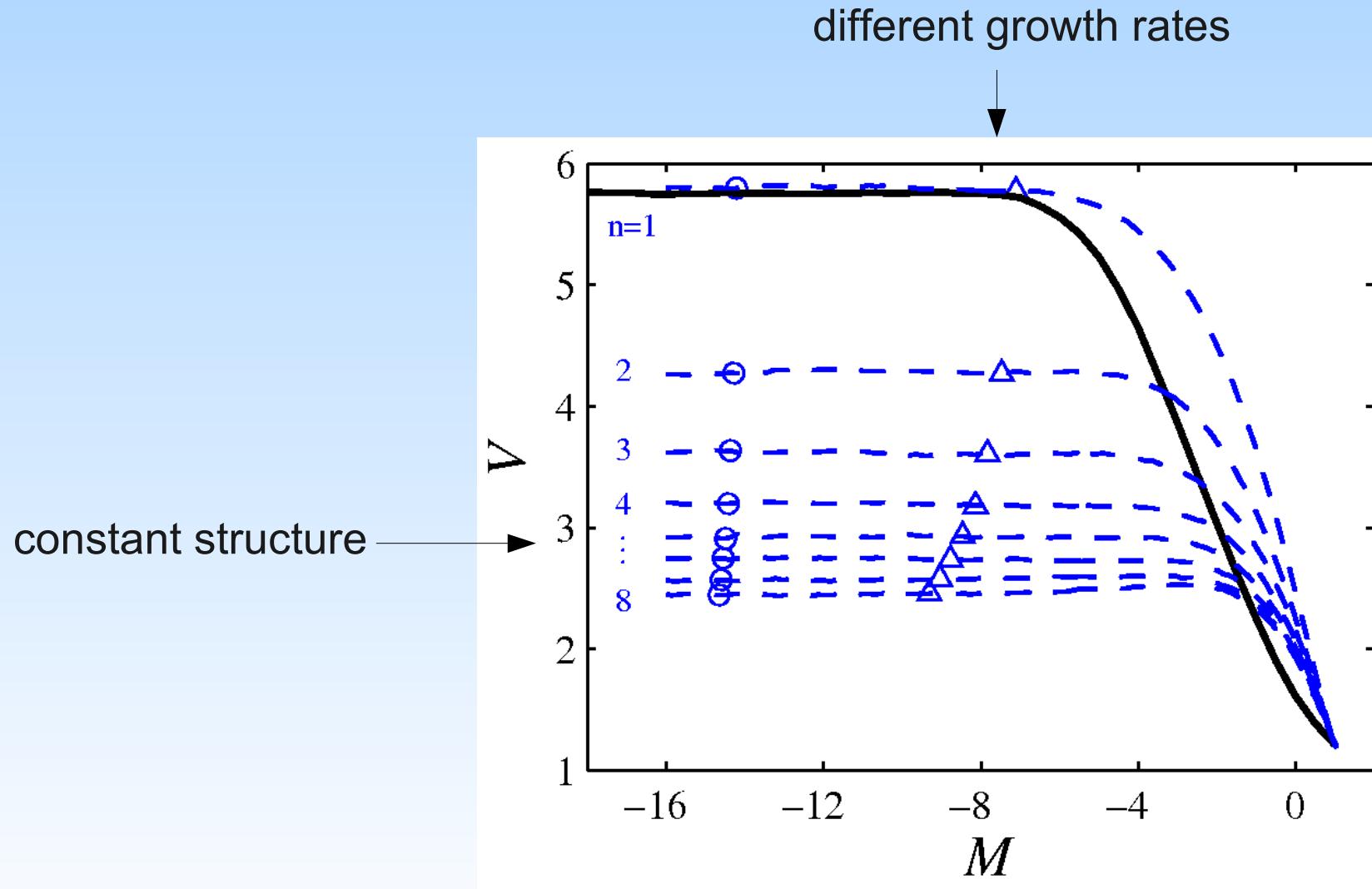
$v(0) \propto$ Singular vector



Dip due to bad adaptation to the flow

RESULTS

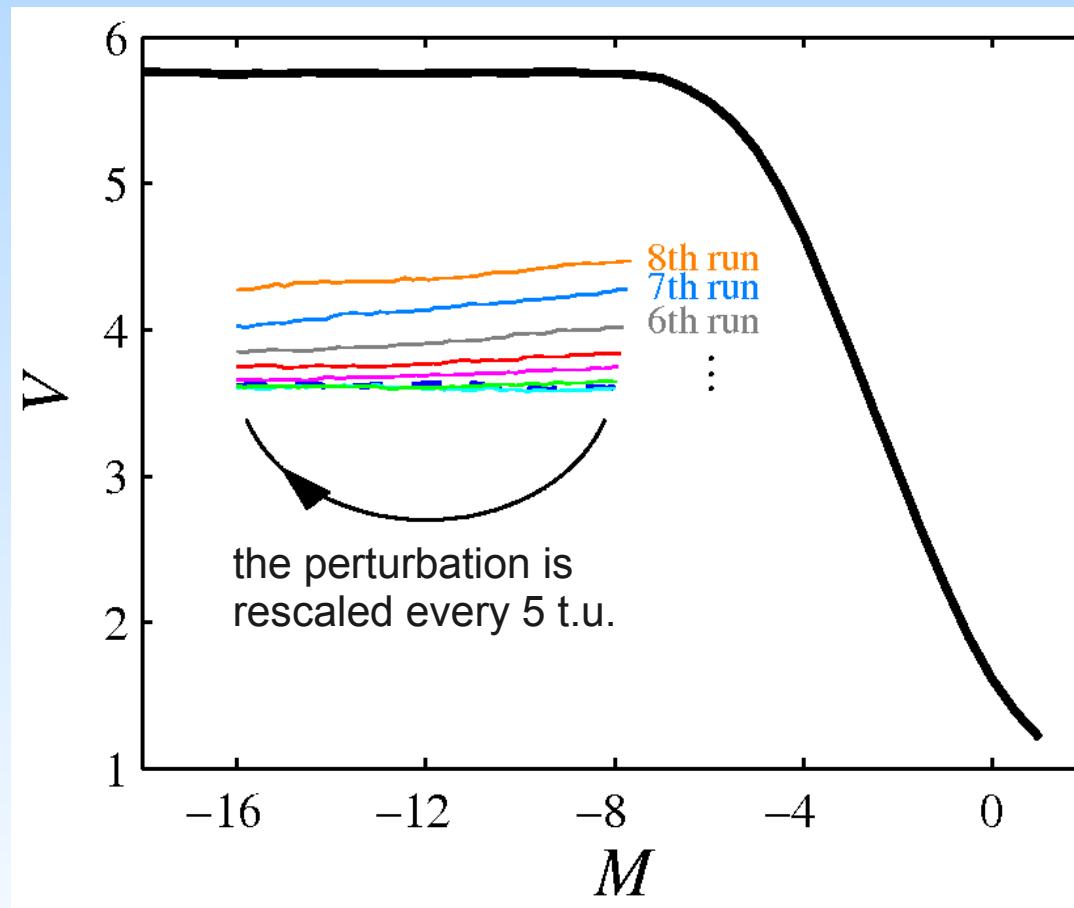
3. Characteristic Lyapunov vectors permit to control growth rate and structure.



RESULTS

4. Characteristic Lyapunov vectors. Robustness!

$\mathbf{v}(0) \propto$ 3-rd Characteristic Lyapunov vector



CONCLUSIONS

- ◆ Vectors evolved from the past: well adapted, but common growth rate $\approx \lambda_1$
- ◆ Vectors with information from the future: controllable growth, but badly adapted (strong transients).
- ◆ Characteristic LV:
 - ◆ Well adapted and different growth rates $\{\lambda_n\}$.
 - ◆ Very robust!

THANKS!!

[Miguel A. Rodríguez, Juan M. López, Ivan G. Szendro and Sarah Hallerberg]

Main reference: Pazó et al., Tellus **62A**, 10-23 (2010)
[<http://www.ifca.unican.es/~pazo>]