

# Computational Physics 2

## Administrative

Lecturer: me

Lectures: Thursdays 12noon - 1pm

Labs: Thursdays 2pm - 4pm

Mark distribution: Cont.assessment  
(= quizzes + assignments)  $\rightarrow$  30%  
Exam  $\rightarrow$  70%

MP468P Project: (dual-department students) Oct–May

# Overview of lecture slides 00

- 1 Content/overview of module
- 2 The unix/linux command line
- 3 Programming language(s) — choice of python
- 4 Changing landscape of computational physics
- 5 Things not covered
- 6 The practice of scientific computing
- 7 You should...

# Computational Physics 2: Content

## Module topics

- Random numbers and stochastic processes
- Monte Carlo methods
- Linear algebra  
(Linear sets of equations, matrix decompositions, eigenvalues)
- Minimisation / Optimisation
- Partial differential equations (PDEs)  
+ ODE boundary value problems
- “Soft skills”: unix/linux command-line, python

## Computational Physics 2: Specialties

This module is a bit different...

- Components of  $\left\{ \begin{array}{l} \text{Math (linear algebra, PDE's)} \\ \text{Statistics (random processes, probability)} \\ \text{Computer Science (Algorithms)} \end{array} \right.$
- 'Lab' work
- May turn out to be the most useful subject for your future
- The most 'modern' module.  
(Numerics with python — less than 20 years old)
- Some aspects will become outdated in a few years.  
(Programming tools, workflow, etc. Not the principles.)

# The command line

## Why unix systems, why command line?

- Serious computing generally done on unix/linux machines
- Serious computing usually done **remotely** on multiple machines/cores
  - ▶ at high-performance computing facilities (e.g., ICHEC in Ireland)
  - ▶ wherever you have access to multiple cpu's or gpu's
  - ▶ Difficult to work remotely without command-line knowledge!

# The command line

## Common commands

- Basic: `ls`, `cd`, `cp`, `mv`, `rm`, `mkdir`, `less`, `grep`, `diff`, `cat`, `top`, `ps`, `kill`
- Slightly less basic:  
`ssh`, `find`, `awk`, `tar`, `sort`, `gzip`, `unzip`, `chmod`, `chown`, `tail`, `head`

## Combinations

- **Piping** the results of one command (program) into another:  
`ls | sort -r`      `ls -l | sort -g -k 5`      `cat *.tex | grep -i perturbative`
- **Redirection**: output of one command sent to a file:  
`cat file1.txt file2.txt > outfile.txt`

## Computer languages other than python

Should you learn other programming languages?

C? julia? Fortran? Mathematica? matlab/octave? maple?

SageMath? R? html? java? javascript? C++? Go?

lisp? php? perl? bash? awk & sed? Ruby? C#?

Pascal? COBOL? Basic? Assembly language? POV-Ray?

# Computer languages

## Low-level vs High-level

- Low-level → closer to machine;  
programmer implements many details;  
speed and control at the expense of programmer time.
- High-level → closer to human;      ≈ **scripting** languages  
programmer uses libraries; pre-defined data structures
- Nowadays, low-level ≈ compiled; high-level ≈ interpreted.

### Low-level languages:

(low to high)

Machine language  
Assembly language  
C / Fortran

### High-level languages:

python / julia / matlab  
Mathematica / Maple  
awk / bash / perl



# Using python for computational physics

## Python: the best programming language ever (?)

- Widely used — lots of information easily available
- Easy to learn  
interpreted not compiled, don't have to worry about variable types
- Libraries available for many common (and specialized) tasks.
  - ▶ Most relevant for us: [numpy](#), [scipy](#), [matplotlib](#)
- Speed does not matter nowadays for many tasks.
  - ▶ Many tasks done by external, non-python libraries.  
Example: matrix eigensolvers call 'lapack' library.
- Counting starts at 0 instead of 1, like a proper computer language.

# Using python for computational physics

## Python: a terrible choice of programming language

- Widely used — lots of junk information and incompetent users
- Slow. Very, very slow. Crawling slow.  
interpreted not compiled
- Sometimes speed actually matters.
  - ▶ E.g., Monte Carlo calculations.
  - ▶ To speed up critical parts of your code, you might have to write those parts in C/Fortran. → two-language problem
- Designed originally for computer people, not for physicists or for numerical work. We are secondary citizens in the python world. Sometimes this shows :-(
- Counting starts at 0 instead of 1, an insult to people who deal with matrices and vectors.

# Alternatives to python

## Matlab/octave

- **Pros:** Designed for numerical work. Just-In-Time compiler makes matlab faster than python. Octave freely available. Packages less chaotic than for python.
- **Cons:** Matlab needs expensive license. Octave slower. Not a proper programming language.

## C/ C++

- **Pros:** Fast if coded correctly.
- **Cons:** Have to learn a (much) more complicated language than python. Compilation necessary — development cycle slower. Memory allocations by hand. Not as many convenient predefined data structures. Using libraries is a more involved process.

## Alternatives to python, continued

### Fortran

- **Pros:** Designed explicitly for numerical work. Fast if coded correctly.
- **Cons:** Compilation cycle. Not used much outside numerics.

### julia

- **Pros:** Designed explicitly for numerical work.  
Aims to solve the two-language problem — aims to be fast to develop and fast to run. Aims to overcome deficits of python.
- **Cons:** Still new, and changing/growing.  
E.g., libraries currently even more chaotic than python.

## Alternatives to python, continued further

### Mathematica/ Maple

- **Pros:** Combination of numerical and symbolic capabilities.
- **Cons:** Not free or open-source. Expensive license.  
Not general-purpose programming languages.

### R

- **Pros:** Great for statistics. Great graphics package.
- **Cons:** Slow. Not as suitable for non-statistical tasks.

# Changing landscape of computational physics

## Algorithms and principles

- Mostly stable, but some things change
- Example: gradient descent

## Changing landscape...

### Programming practices (and fashions)

- Rapid change — be warned (and be prepared)
- python was considered unacceptably slow for numerics, until  $\sim$ 2005.
- double precision was considered unacceptably slow for numerics.
- integer division, different in python2 and python3.
- GPU usage increasingly unavoidable. :-)
- For scientific usage, python might be replaced by julia soon(ish).

# Things not covered in MP468C

- Many, many aspects of numerical analysis!!  
Graph algorithms, advanced data structures, adaptive numerical integration, extrapolation, finite element methods, ....
- Serious applications of computers in physics  
Quantum Monte Carlo, molecular dynamics, density functional theory,....
- Statistical data analysis, Machine learning
- Parallel computing
- GPU computing
- Cloud computing
- Other programming languages/paradigms: Matlab/octave, mathematica, julia, C, ...
- Many python features: objects/classes, sympy, making packages,...



# The practice of computational physics

## Do's and don't's

- Don't **guess** what a command/package does. Look it up.  
E.g., If you use `np.arange(2,10)`, first read its doc.
- Looking up documentation: use **reliable** sources.
- Start coding first, think later?

Please please please don't!!!

- First calculate by hand (on paper) whatever is needed.  
When possible: write out what you need to code as **pseudocode** or as an algorithm.

# Practice — writing out algorithms

## Example (from wikipedia page on Metropolis-Hastings)

### 1. Initialise

1. Pick an initial state  $x_0$ .
2. Set  $t = 0$ .

### 2. Iterate

1. *Generate* a random candidate state  $x'$  according to  $g(x' | x_t)$ .
2. *Calculate* the acceptance probability  $A(x', x_t) = \min \left( 1, \frac{P(x') g(x_t | x')}{P(x_t) g(x' | x_t)} \right)$ .
3. *Accept or reject*:
  1. generate a uniform random number  $u \in [0, 1]$ ;
  2. if  $u \leq A(x', x_t)$ , then *accept* the new state and set  $x_{t+1} = x'$ ;
  3. if  $u > A(x', x_t)$ , then *reject* the new state, and copy the old state forward  $x_{t+1} = x_t$ .
4. *Increment*: set  $t = t + 1$ .

# Writing out algorithms

Example from Higham, *Accuracy & Stability of Numerical Algorithms*

Power method  
for finding eigenvalues

```
% Choose a starting vector  $x$ .  
while not converged  
     $x := Ax$   
     $x := x/\|x\|_\infty$   
end
```

# Writing out algorithms

Another example from Higham, *Accuracy & Stability...*

Computing the  
QR decomposition  
of an  $n \times n$  matrix  $A$ , using a  
Gram-Schmidt-like method.

```
 $a_k^{(1)} = a_k, k = 1:n$   
for  $k = 1:n$   
   $r_{kk} = \|a_k^{(k)}\|_2$   
   $q_k = a_k^{(k)} / r_{kk}$   
  for  $j = k+1:n$   
     $r_{kj} = q_k^T a_j^{(k)}$   
     $a_j^{(k+1)} = a_j^{(k)} - r_{kj} q_k$   
  end  
end
```

# Writing out algorithms

## Example from Kreyszig, *Advanced Engineering Mathematics*

ALGORITHM RUNGE-KUTTA ( $f, x_0, y_0, h, N$ ).

This algorithm computes the solution of the initial value problem  $y' = f(x, y)$ ,  $y(x_0) = y_0$  at equidistant points

$$(9) \quad x_1 = x_0 + h, x_2 = x_0 + 2h, \dots, x_N = x_0 + Nh;$$

here  $f$  is such that this problem has a unique solution on the interval  $[x_0, x_N]$  (see Sec. 1.7).

INPUT: Function  $f$ , initial values  $x_0, y_0$ , step size  $h$ , number of steps  $N$

OUTPUT: Approximation  $y_{n+1}$  to the solution  $y(x_{n+1})$  at  $x_{n+1} = x_0 + (n + 1)h$ , where  $n = 0, 1, \dots, N - 1$

For  $n = 0, 1, \dots, N - 1$  do:

$$k_1 = hf(x_n, y_n)$$

$$k_2 = hf(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_1)$$

$$k_3 = hf(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_2)$$

$$k_4 = hf(x_n + h, y_n + k_3)$$

$$x_{n+1} = x_n + h$$

$$y_{n+1} = y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

OUTPUT  $x_{n+1}, y_{n+1}$

End

Stop

End RUNGE-KUTTA

# Writing out algorithms

## Another example from Kreyszig, *Adv. Eng. Math.*

**Table 20.2** Gauss–Seidel Iteration

ALGORITHM GAUSS–SEIDEL ( $\mathbf{A}$ ,  $\mathbf{b}$ ,  $\mathbf{x}^{(0)}$ ,  $\epsilon$ ,  $N$ )

This algorithm computes a solution  $\mathbf{x}$  of the system  $\mathbf{Ax} = \mathbf{b}$  given an initial approximation  $\mathbf{x}^{(0)}$ , where  $\mathbf{A} = [a_{jk}]$  is an  $n \times n$  matrix with  $a_{jj} \neq 0$ ,  $j = 1, \dots, n$ .

INPUT:  $\mathbf{A}$ ,  $\mathbf{b}$ , initial approximation  $\mathbf{x}^{(0)}$ , tolerance  $\epsilon > 0$ , maximum number of iterations  $N$

OUTPUT: Approximate solution  $\mathbf{x}^{(m)} = [x_j^{(m)}]$  or failure message that  $\mathbf{x}^{(N)}$  does not satisfy the tolerance condition

For  $m = 0, \dots, N - 1$ , do:

For  $j = 1, \dots, n$ , do:

$$1 \quad \left| \quad \begin{array}{l} x_j^{(m+1)} = \frac{1}{a_{jj}} \left( b_j - \sum_{k=1}^{j-1} a_{jk} x_k^{(m+1)} - \sum_{k=j+1}^n a_{jk} x_k^{(m)} \right) \end{array} \right.$$

End

2 If  $\max_j |x_j^{(m+1)} - x_j^{(m)}| < \epsilon$  then OUTPUT  $\mathbf{x}^{(m+1)}$ . Stop

[Procedure completed successfully]

End

OUTPUT: “No solution satisfying the tolerance condition obtained after  $N$  iteration steps.” Stop

[Procedure completed unsuccessfully]

End GAUSS–SEIDEL

## How you can help (yourself and me)

### Would help if you...

- Keep learning python and numpy intricacies —  
read sections of the official documentation  
(or a good book) as bedtime reading
- Install a linux/unix shell (a bash shell) on your own machine.