

# Overview of slides 08

- 1 Initial value problems for pdes
  - Stability issues
  - The FTCS scheme
  - Improved discretisation schemes
  - Implicit schemes
  - The Crank–Nicolson scheme
  - Schrödinger equation
- 2 Wave equation
- 3 Relaxation methods for BVPs
- 4 Summary

## Boundary and initial value problems

We looked at boundary value problems, which may be solved in a similar way to boundary-value odes.

Now: **initial value problems**.

Start with diffusion equation in 1+1 dimension:

Diffusion equation

$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2}$$

Identical to **heat equation**.

Similar to **Schroedinger equation** in 1+1 dimension.

## Initial value problems for pdes

Diffusion equation in 1+1 dimension:

$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2}$$

### Discretise space & time.

Using grid spacings  $\Delta x = a$  in space,  $\Delta t$  in time, we write

$$u(x_i, t_n) = u(x_0 + ia, t_0 + n\Delta t) \equiv u_i^{(n)}.$$

Take **forward derivative** in time, and **symmetric second derivative** in space:

**F**orward **T**ime, **C**entred **S**pace

$$\begin{aligned} \frac{\partial u}{\partial t} &= \frac{u_j^{(n+1)} - u_j^{(n)}}{\Delta t} = D \frac{\partial^2 u}{\partial x^2} = \frac{D}{a^2} \left( u_{j-1}^{(n)} - 2u_j^{(n)} + u_{j+1}^{(n)} \right) \quad (1) \\ \implies u_j^{(n+1)} &= \left( 1 - \frac{2\Delta t}{a^2} \right) u_j^{(n)} + \frac{\Delta t}{a^2} \left( u_{j+1}^{(n)} + u_{j-1}^{(n)} \right) \end{aligned}$$

It is straightforward to iterate this forward in time from  $n = 0$ .

# Stability issues

- Discretization of time-dep PDE's often leads to instabilities 😞
  - ▶ If discretization scheme is unstable, small errors blow up with time evolution.
  - ▶ Origin of errors? E.g., machine precision
  - ▶ Error in each step can be, e.g., of order  $\Delta t(\Delta x)^2$   
Instability is due to continued time evolution, not single-step error
- Think of  $u^{(m)}$  as a vector at each timestep.  
Explicit schemes like FTCS:  $u^{m+1} = Au^m$   
Scheme is stable if  $A$  has  $|\text{eigenvalues}| < 1$ .  
Alternative analysis: von Neumann stability analysis
- Later: implicit schemes:  $Bu^{m+1} = Au^m$

# Stability analysis

## von Neumann analysis

Fourier transform in space:  $u(x) = \sum_k e^{ikx} u(k)$

Each  $u(k)$  evolves independently in time

(at least for linear problems with constant coeffs)

This gives the **eigenmode evolution**

$$u_k^{(n+1)} = \xi_k u_k^{(n)} \quad \Longrightarrow \quad u_j^{(n)} = u_0^{(0)} (\xi_k)^n e^{ikja} \quad (2)$$

To find **amplification factor**  $\xi_k$ , substitute (2) into finite difference equation

$$|\xi_k| \begin{cases} > 1 & \text{exponential growth, instability} \\ < 1 & \text{exponential damping, stability} \\ = 1 & \text{more detailed analysis needed} \end{cases}$$

**von Neumann stability:**  $|\xi_k| \leq 1 \quad \forall k \quad (\text{for ALL } k)$

## Stability for FTCS

Inserting the eigenmode evolution (2) into the FTCS equation (1) gives

$$\frac{\xi_k^{n+1} e^{ijka} - \xi_k^n e^{ijka}}{\Delta t} = \frac{D}{a^2} \xi_k^n \left( e^{ik(j-1)a} - 2e^{ikja} + e^{ik(j+1)a} \right)$$

$$\xi_k = 1 + \frac{D\Delta t}{a^2} \left( e^{-ika} - 2 + e^{ika} \right) = 1 - \frac{4D\Delta t}{a^2} \sin^2 \frac{ka}{2}$$

This is always  $\leq 1 \implies$  stability requires  $\xi_k \geq -1$

$$\implies \frac{4D\Delta t}{a^2} \sin^2 \frac{ka}{2} \leq 2.$$

'Worst case':  $\sin^2(ka/2) = 1$

$$\text{Stability condition: } \frac{\Delta t}{a^2} \leq \frac{1}{2D}$$

## An example

The python file `ftcs_driver.py` solves the diffusion equation with the initial distribution

$$u_0(x) = u(x, t_0) = e^{-x^2/4Dt_0}, \quad -5 \leq x \leq 5, t_0 = 0.1,$$

and boundary conditions

$$u(\pm x_0, t) = \sqrt{\frac{t_0}{t}} e^{-x_0^2/4Dt}, \quad x_0 = 5.$$

The grid spacing in the  $x$  direction has been set to  $a = 0.05$ , and the diffusion constant  $D = 1$ .

`ftcs_driver(dt, t)` plots the solution for time step  $dt$  at time(s)  $t$ .

Run this with  $dt=0.0012$  and see what you get.

Then run with  $dt=0.0013$  and see what happens.

## FTCS in 2+1 dimension

Our Ansatz is now

$$u_{jl}^{(n)} = u_0 \xi_k^n e^{ik_x j \Delta x} e^{ik_y l \Delta y} \quad (3)$$

For  $\Delta x = \Delta y = a$  the FTCS scheme is

$$\frac{u_{jl}^{(n+1)} - u_{jl}^{(n)}}{\Delta t} = \frac{D}{a^2} \left( u_{j-1,l}^{(n)} + u_{j,l-1}^{(n)} + u_{j+1,l}^{(n)} + u_{j,l+1}^{(n)} - 4u_{jl}^{(n)} \right)$$

Inserting (3) gives

$$\begin{aligned} \xi_k &= 1 + \frac{D\Delta t}{a^2} \left( e^{-ik_x a} + e^{-ik_y a} + e^{ik_x a} + e^{ik_y a} - 4 \right) \\ &= 1 - \frac{4D\Delta t}{a^2} \left( \sin^2 \frac{k_x a}{2} + \sin^2 \frac{k_y a}{2} \right) \end{aligned}$$

$$|\xi_k| \leq 1 \quad \forall k \quad \implies \quad \frac{\Delta t}{a^2} \leq \frac{1}{4D}$$



## Improving stability (want to use larger $\Delta t$ )

### Stability condition is quite severe



- We want to model features at large scales  $\lambda \gg a$   
Typical diffusion time is  $\tau \sim \lambda^2/D$   
→ need  $n = \frac{\tau}{\Delta t} \sim \frac{\lambda^2}{a^2}$  time steps
- We want to improve accuracy by reducing  $a$   
But if  $a \rightarrow a/2$  then  $\Delta t \rightarrow \Delta t/4$   
→ 8 times as much cpu time!

Can we improve on this?

## Second order time derivative?

FTCS is first-order accurate in time, second order in space

What about using second-order differencing in time?

### Centred Time Centred Space

$$\frac{u_j^{(n+1)} - u_j^{(n-1)}}{2\Delta t} = \frac{D}{a^2} \left( u_{j-1}^{(n)} - 2u_j^{(n)} + u_{j+1}^{(n)} \right)$$

### von Neumann

$$\xi_k - \frac{1}{\xi_k} = -\frac{8D\Delta t}{a^2} \sin^2 \frac{ka}{2}$$
$$\Rightarrow \xi_k = -\frac{4D\Delta t}{a^2} \sin^2 \frac{ka}{2} \pm \sqrt{1 + \left( \frac{4D\Delta t}{a^2} \sin^2 \frac{ka}{2} \right)^2}$$

The  $(-)$  mode is unstable for **all**  $k$  and  $\Delta t$ !

**CTCS is unconditionally unstable**

## Implicit schemes: BTCS

**Explicit** scheme:  $\frac{\partial^2 u}{\partial x^2}$  evaluated at  $t$

**Implicit** scheme: evaluate at  $t + \Delta t$

### Backward Time, Centred Space

$$\frac{u_j^{(n+1)} - u_j^{(n)}}{\Delta t} = \frac{u_{j-1}^{(n+1)} - 2u_j^{(n+1)} + u_{j+1}^{(n+1)}}{a^2}$$
$$\implies \left(1 + \frac{2\Delta t}{a^2}\right) u_j^{(n+1)} - \frac{\Delta t}{a^2} \left(u_{j-1}^{(n+1)} + u_{j+1}^{(n+1)}\right) = u_j^{(n)}$$

We get a sparse matrix equation for  $u^{(n+1)}$ .

### von Neumann analysis

$$\frac{\xi - 1}{\Delta t} = \frac{\xi}{a^2} \left( e^{ika} - 2 + e^{-ika} \right) \implies \xi = \frac{1}{1 + \frac{4\Delta t}{a^2} \sin^2 \frac{ka}{2}}$$

$\xi < 1$  for **all**  $k, \Delta t$ : BTCS is **unconditionally stable**

# Crank–Nicolson

BTCS is stable, but only first-order accurate in time.

How can we get second-order accuracy?

Average FTCS and BTCS!

(the same as taking a centred time derivative around  $t + \Delta t/2$ )

$$\frac{u_j^{(n+1)} - u_j^{(n)}}{\Delta t} = \frac{1}{2a^2} \left[ \underbrace{u_{j+1}^{(n+1)} - 2u_j^{(n+1)} + u_{j-1}^{(n+1)}}_{BTCS} + \underbrace{u_{j+1}^{(n)} - 2u_j^{(n)} + u_{j-1}^{(n)}}_{FTCS} \right]$$

## Crank–Nicolson

$$\left(1 + \frac{\Delta t}{a^2}\right) u_j^{(n+1)} - \frac{\Delta t}{2a^2} (u_{j-1}^{(n+1)} + u_{j+1}^{(n+1)}) = \left(1 - \frac{\Delta t}{a^2}\right) u_j^{(n)} + \frac{\Delta t}{2a^2} (u_{j-1}^{(n)} + u_{j+1}^{(n)})$$

# Stability of Crank-Nicolson

## von Neumann analysis

$$\xi \left( 1 - \frac{-4\Delta t}{2a^2} \sin^2 \frac{ka}{2} \right) = 1 + \frac{-4\Delta t}{2a^2} \sin^2 \frac{ka}{2}$$
$$\implies \boxed{\xi = \frac{1 - \frac{2\Delta t}{a^2} \sin^2 \frac{ka}{2}}{1 + \frac{2\Delta t}{a^2} \sin^2 \frac{ka}{2}}} = \frac{1 - b^2}{1 + b^2}$$

The modulus of the numerator is always smaller than the denominator

Crank-Nicolson is unconditionally stable

## Price of stability

BTCS and Crank-Nicolson are stable, but

**implicit** methods: need to solve linear set of equations **at each step**

$Bu^{(m+1)} = Au^{(m)}$   $\longrightarrow$  pre-factorize  $B$  ( $LU$  or Cholesky)

## Schrödinger equation

$$i\hbar \frac{\partial \Psi}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \Psi + V(\vec{x})\Psi$$

This can be discretised in the same way as diffusion equation

### Important constraint

Time evolution is **unitary**  $\iff$  Total probability is conserved

$$\text{Formally: } \Psi(t) = e^{-iH(t-t_0)/\hbar} \Psi(t_0)$$

### FTCS for Schrödinger equation

$$\Psi^{(n+1)} = \Psi^{(n)} - \frac{i\Delta t}{\hbar} H \Psi^{(n)} = \left(1 - \frac{i\Delta t}{\hbar} H\right) \Psi^{(n)}$$

This is unconditionally unstable, and not unitary!

**BTCS** is **stable**, but still not unitary.

## A unitary evolution operator

Use the **Cayley form** for  $\exp(iH)$ ,

$$e^{iH\Delta t} \approx \frac{1 - \frac{1}{2}iH\Delta t}{1 + \frac{1}{2}iH\Delta t}$$

This gives us

$$\left(1 + \frac{1}{2}iH\Delta t\right)\Psi^{(n+1)} = \left(1 - \frac{1}{2}iH\Delta t\right)\Psi^{(n)}$$

This is Crank–Nicolson again!

**Stable**, second-order accurate and **unitary**.

# Schrödinger equation

## Widely used methods

- Crank-Nicholson type methods  
Price: solving linear system at each step
- Spectral methods with time splitting

$$\psi(t + \epsilon) = e^{-(i/\hbar)(\hat{T} + \hat{V})\epsilon} \psi(t) \approx e^{-(i/\hbar)\hat{T}\epsilon/2} e^{-(i/\hbar)\hat{V}\epsilon} e^{-(i/\hbar)\hat{T}\epsilon/2} \psi(t)$$

Evolve with  $\hat{T}$  in Fourier space, evolve with  $\hat{V}$  in real space.

Price: Fourier and inverse Fourier transforms at each step.



## Wave equation

Examples too numerous to list. . .

$$\frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = 0$$

has formal solution

$$u(x, t) = F(x - ct) + G(x + ct), \quad \text{any } F, G$$

The equation can be discretised directly (using **staggered leapfrog** scheme) or transformed to two coupled first-order equations,

$$\begin{aligned} \frac{\partial v}{\partial t} + c \frac{\partial w}{\partial x} &= 0, & \frac{\partial w}{\partial t} + c \frac{\partial v}{\partial x} &= 0 \\ \text{with } v(x, t) &= \frac{\partial u}{\partial t}, & w(x, t) &= -c \frac{\partial u}{\partial x} \end{aligned}$$

### Courant–Friedrichs–Lewy condition

Any explicit discretisation scheme for **wave** or **advection** equation requires

$$\Delta t < c \Delta x$$

## Relaxation methods

for **static** boundary value problems

We want to solve  $\mathcal{L}\Phi = \rho$ ,  $\mathcal{L} = \text{elliptic operator, eg. } \nabla^2$

Start with initial guess, let system 'relax'  $\rightarrow$  **solution of pde**

### Diffusion in computer time

$$\frac{\partial \Phi}{\partial t} = \mathcal{L}\Phi - \rho \quad \mathcal{L} = \text{elliptic operator, eg. } \nabla^2$$

$\rightarrow$  **stationary** (late time) solution fulfils  $\mathcal{L}\Phi = \rho$

We converted the problem to **initial value PDE**

Applying PDE techniques to solving ODE BVP!!

Common example: **time-independent** Schrödinger equation

$\hat{H}\Psi(x, y) = E\Psi(x, y)$  can be solved for smallest  $E$  by evolving

$$\frac{\partial}{\partial t}\Psi(x, y, t) = \hat{H}\Psi(x, y, t) \text{ to late times}$$

→ propagation in **imaginary time**

# Summary

- von Neumann stability criterion for time evolution equations:
  - ① Fourier transform in space
  - ② Find amplification factor  $\xi_k$  for each mode  $k$
  - ③ Stability  $\iff \xi_k \leq 1$
- Forward Time, Centred Space:  
Explicit, stable for  $\Delta t \leq a^2/2dD$  (1+d dim)
- Backward Time, Centred Space:  
Implicit, unconditionally stable
- Both FTCS and BTCS are first order in time
- Crank–Nicolson: Average FTCS and BTCS.  
Second order in time, unconditionally stable, widely used
- Relaxation: applying PDE techniques to ODE BVP's